Topologically massive gravity and the AdS/CFT correspondence

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# Topologically massive gravity and the AdS/CFT correspondence 

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Abstract: We set up the AdS/CFT correspondence for topologically massive gravity (TMG) in three dimensions. The first step in this procedure is to determine the appropriate fall off conditions at infinity. These cannot be fixed a priori as they depend on the bulk theory under consideration and are derived by solving asymptotically the non-linear field equations. We discuss in detail the asymptotic structure of the field equations for TMG, showing that it contains leading and subleading logarithms, determine the map between bulk fields and CFT operators, obtain the appropriate counterterms needed for holographic renormalization and compute holographically one- and two-point functions at and away from the "chiral point" $(\mu=1)$. The 2 -point functions at the chiral point are those of a logarithmic CFT (LCFT) with $c_{L}=0, c_{R}=3 l / G_{N}$ and $b=-3 l / G_{N}$, where $b$ is a parameter characterizing different $c=0$ LCFTs. The bulk correlators away from the chiral point $(\mu \neq 1)$ smoothly limit to the LCFT ones as $\mu \rightarrow 1$. Away from the chiral point, the CFT contains a state of negative norm and the expectation value of the energy momentum tensor in that state is also negative, reflecting a corresponding bulk instability due to negative energy modes.

Keywords: Gauge-gravity correspondence, AdS-CFT Correspondence

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## 1 Introduction

Although three-dimensional Einstein gravity is locally trivial, this is generally no longer the case once higher-derivative terms are added to the action. The addition of such terms provides the theory with propagating degrees of freedom, i.e. three-dimensional gravitons. The quantization of such theories therefore appears to give a richer structure than the Einstein theory, yielding potentially interesting toy models for higher-dimensional theories of quantum gravity.

Unfortunately, the addition of generic higher-derivative terms to the Einstein-Hilbert action often gives ghost-like excitations which render the theory unstable. Recently a renewed interest has been taken in the so-called topologically massive (cosmological) gravity $[1,2]$, or TMG for short. This theory consists of the Einstein-Hilbert action with a negative cosmological constant plus a gravitational Chern-Simons term

$$
\begin{equation*}
S_{\mathrm{cs}}=\frac{1}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{-G} \epsilon^{\lambda \mu \nu}\left(\Gamma_{\lambda \sigma}^{\rho} \partial_{\mu} \Gamma_{\rho \nu}^{\sigma}+\frac{2}{3} \Gamma_{\lambda \sigma}^{\rho} \Gamma_{\mu \tau}^{\sigma} \Gamma_{\nu \rho}^{\tau}\right) \tag{1.1}
\end{equation*}
$$

Although adding a Chern-Simons term likely leads to instabilities for general values of the dimensionless parameter $\mu$, it was argued in [3] that the theory becomes stable and chiral when $\mu=1$. At that point, which we will call the "chiral point", all the leftmoving excitations of the theory would become pure gauge and one would effectively have a right-moving theory.

Other authors however found non-chiral modes at the chiral point, [4-11] (see however also [12]). In particular in [5] a left-moving excitation of the linearized equations of motion was explicitly written down ${ }^{1}$. From the transformation properties of the new mode of [5] under the $\left(L_{0}, \bar{L}_{0}\right)$ operators one found a structure typical of a logarithmic conformal field theory (LCFT) and consequently it was claimed that the theory with $\mu=1$ was dual to such a theory. Since LCFTs are not chiral (and not unitary either), this provided a further argument against the conjecture.

However, near the conformal boundary the new mode does not obey the same falloff conditions as the other modes. This has led to claims that one can ignore the new mode by imposing strict 'Brown-Henneaux' [15] boundary conditions: the new mode does not

[^0]satisfy these so it then has to be discarded and the resulting theory could again be chiral [16]. In [10] a non-chiral mode of the linearized equations of motion, related to that of Grumiller and Johansson but satisfying the Brown-Henneaux boundary conditions, was found. However, [17] argued that this mode is not a linearization of a non-linear solution. This linearization instability was further discussed in [18]. On the other hand, in [19, 20] it was claimed that the Brown-Henneaux boundary conditions could be relaxed to incorporate the non-chiral mode without destroying the consistency of the theory. At first sight one seems to be free to choose either set of boundary conditions, supposedly leading to a different theory for each possibility [17].

The topologically massive theory admits solutions that are asymptotically AdS so one can use the AdS/CFT correspondence to analyze the theory. This is the viewpoint pursued in this paper. One of the cornerstones of the AdS/CFT correspondence is that the boundary fields parameterizing the boundary conditions of the bulk fields are identified with the sources for the dual operators. It follows that the leading boundary behavior must be specified by unconstrained fields, whereas the subleading radial behavior of the fields is determined dynamically by the equations of motion and should not be fixed by hand. Putting it differently, the subleading radial behavior is obtained by finding the most general asymptotic solution to the field equations given boundary data. For theories that admit asymptotically locally AdS solutions the most general asymptotic solution, which is sometimes called the "Fefferman-Graham" expansion, can always be found by solving algebraic equations, see [21] for a review. We would like to emphasize that the FeffermanGraham expansion does not have a predetermined form, as is sometimes stated in the literature, but rather the form of the expansion is dynamically determined.

For theories that admit asymptotically (locally) AdS solutions finite conserved charges can always be obtained [22-27] via the formalism of holographic renormalization [21]. In particular, ref. [27] provides a first principles proof that the holographic charges are the correct gravitational conserved charges for Asymptotically locally AdS spacetimes. One should contrast the logic here with what is usually done in other papers. The discussion there starts by selecting fall off conditions for all fields, for example Brown-Henneaux boundary conditions, such that interesting known solutions (such as black holes etc.) are within the allowed class and then it is checked whether these boundary conditions lead to finite conserved charges. On the other hand, here we start by deriving the most general Asymptotically locally AdS boundary conditions. Finite conserved charges (which satisfy all expected properties) are guaranteed by the general results of [27]. Note that the finite conserved charges are related to the 1-point function of the dual energy momentum tensor via the AdS/CFT dictionary. The next simplest quantities to compute are the 2 -point functions of the dual operators. These are obtained from solutions of the linearized equations of motion with Dirichlet boundary conditions.

In this paper we develop the AdS/CFT dictionary for topologically massive gravity. We obtain the most general asymptotic solutions that are Asymptotically locally AdS and compute the holographic one- and two-point functions of the theory at and away from the chiral point. One new feature in this case is that the field equations are third order in derivatives. Ordinarily higher derivative terms are treated as perturbative corrections to
two derivative actions and as such they do not change the usual AdS/CFT set-up. In the case of TMG, however, we need to treat the Einstein and Chern-Simons terms on equal footing. The fact that the field equation is third order implies that there is an additional piece of boundary data to be specified. This means that we can fix both a boundary metric (or more precisely, a conformal class) and (part of) the extrinsic curvature. The boundary metric acts as a source for the boundary stress energy tensor, while the field parametrizing the boundary condition for the extrinsic curvature is a source for a new operator. It turns out that this operator is irrelevant when $\mu>1$ and it becomes the logarithmic partner of the stress energy tensor as $\mu \rightarrow 1$.

The asymptotic expansion at $\mu=1$ contains the subleading log piece found earlier in [5]. The coefficient of this term corresponds to the 1-point function of the logarithmic partner of the energy momentum tensor. As this operator is obtained as a limit of an irrelevant operator, its source (as usual) should be treated perturbatively. This source, which is the above mentioned boundary condition for the extrinsic curvature, appears as the coefficient of a leading order log term in the solution to the linearized equations of motion (not to be confused with the subleading log of [5] which relates to the 1-point function of this operator). The results for the two-point functions at $\mu=1$ completely agree with LCFT expectations and the results away from $\mu=1$ smoothly limit to the $\mu=1$ results. Bulk instabilities when $\mu \neq 1$ due to negative energy modes also neatly map to properties of the boundary theory, namely negative norm states and correspondingly negativity of the expectation value of the energy momentum tensor in these states.

The remainder of the paper is structured as follows. After discussing some conventions and giving the equations of motion, we review in section 3 the standard AdS/CFT dictionary, in particular the definition of Asymptotically locally AdS spacetimes, and point out several subtleties which will be crucial in its application to TMG. In section 4 we analyze the asymptotic structure of the bulk solutions for $\mu=1$. We compute the on-shell action, discuss its divergences and the holographic renormalization which enables us to concretely formulate the holographic dictionary. The holographic one point functions satisfy anomalous Ward identities whose interpretation is discussed in section 5 . Section 6 concerns linearized analysis which is used to compute holographically one- and two-point functions for $\mu=1$. We then repeat this analysis for general $\mu$ in section 7 . We end with a short summary and an outlook. Various appendices contain computational details as well as a discussion of some relevant aspects of logarithmic CFTs.

## 2 Setup and equations of motion

The bulk part of the action has the form:

$$
\begin{align*}
S= & \frac{1}{16 \pi G_{N}} \int d^{3} x \sqrt{-G}(R-2 \Lambda) \\
& +\frac{1}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{-G} \epsilon^{\lambda \mu \nu}\left(\Gamma_{\lambda \sigma}^{\rho} \partial_{\mu} \Gamma_{\rho \nu}^{\sigma}+\frac{2}{3} \Gamma_{\lambda \sigma}^{\rho} \Gamma_{\mu \tau}^{\sigma} \Gamma_{\nu \rho}^{\tau}\right), \tag{2.1}
\end{align*}
$$

where we use the covariant $\epsilon$-symbol such that $\sqrt{-G} \epsilon^{012}=1$ with $x^{2}$ the radial direction denoted $\rho$ below. We set $\Lambda=-1$ below. We use the following conventions for the
curvatures:

$$
\begin{equation*}
R_{\mu \nu \rho}{ }^{\sigma}=\partial_{\nu} \Gamma_{\mu \rho}^{\sigma}+\Gamma_{\mu \rho}^{\lambda} \Gamma_{\nu \lambda}^{\sigma}-(\mu \leftrightarrow \nu), \quad \quad R_{\mu \rho}=R_{\mu \sigma \rho}{ }^{\sigma} \tag{2.2}
\end{equation*}
$$

All Greek indices run over three dimensions, all Latin indices over two dimensions. In three dimensions the Weyl tensor vanishes identically, which means that:

$$
\begin{equation*}
R_{\mu \nu \rho \sigma}=G_{\mu \rho} R_{\sigma \nu}-G_{\nu \rho} R_{\sigma \mu}-\frac{1}{2} R G_{\mu \rho} G_{\sigma \nu}-(\rho \leftrightarrow \sigma) . \tag{2.3}
\end{equation*}
$$

The equation of motion derived from (2.1) becomes:

$$
\begin{equation*}
R_{\mu \nu}-\frac{1}{2} G_{\mu \nu} R-G_{\mu \nu}+\frac{1}{\mu} C_{\mu \nu}=0, \tag{2.4}
\end{equation*}
$$

with $C_{\mu \nu}$ the Cotton tensor:

$$
\begin{equation*}
C_{\mu \nu}=\epsilon_{\mu}{ }^{\alpha \beta} \nabla_{\alpha}\left(R_{\beta \nu}-\frac{1}{4} R G_{\beta \nu}\right) . \tag{2.5}
\end{equation*}
$$

Using (2.3) we find that the Bianchi identity becomes:

$$
\begin{equation*}
C_{\mu \nu}-C_{\nu \mu}=0 . \tag{2.6}
\end{equation*}
$$

The last term in the r.h.s. of (2.5) is totally antisymmetric in $\mu$ and $\nu$ and therefore merely subtracts the antisymmetric piece from the first term in the r.h.s. of (2.5). We alternatively have:

$$
\begin{equation*}
C_{\mu \nu}=\frac{1}{2}\left(\epsilon_{\mu}{ }^{\rho \sigma} \nabla_{\rho} R_{\sigma \nu}+\epsilon_{\nu}{ }^{\rho \sigma} \nabla_{\rho} R_{\sigma \mu}\right) . \tag{2.7}
\end{equation*}
$$

It is not hard to verify that

$$
\begin{equation*}
C_{\mu}^{\mu}=0, \quad \nabla_{\mu} C^{\mu \nu}=0 . \tag{2.8}
\end{equation*}
$$

Taking the trace of (2.4) we therefore find that:

$$
\begin{equation*}
R=-6, \tag{2.9}
\end{equation*}
$$

independent of $\mu$. Substituting this back, we find:

$$
\begin{equation*}
R_{\mu \nu}+2 G_{\mu \nu}+\frac{1}{\mu} \epsilon_{\mu}{ }^{\rho \sigma} \nabla_{\rho} R_{\sigma \nu}=0, \tag{2.10}
\end{equation*}
$$

from which we also obtain that any solution to the Einstein equations has $R_{\mu \nu}=-2 G_{\mu \nu}$ and is a solution to these equations as well.

## 3 Asymptotically AdS spacetimes and holography

In this section we will explain what Asymptotically (locally) AdS, or A(1)AdS spacetimes are and their role in the AdS/CFT correspondence. Reviews of the mathematical aspects discussed here can be found in [28, 29]. After introductory comments that are generally applicable, we highlight two aspects of the framework that will be important for its application to TMG, namely irrelevant deformations and higher-derivative terms.

### 3.1 Conformally compact manifolds

First of all, we define a $D$-dimensional conformally compact manifold-with-metric $(M, G)$ as follows. Let $M$ be the interior of a manifold $\bar{M}$ with boundary $\partial M .{ }^{2}$ Suppose there exists a smooth, non-negative defining function $z$ on $\bar{M}$ such that $z(\partial M)=0, d z(\partial M) \neq 0$ and the metric

$$
\begin{equation*}
\tilde{G}=z^{2} G \tag{3.1}
\end{equation*}
$$

extends smoothly to a non-degenerate metric on $\bar{M}$. We then say that $(M, G)$ is conformally compact and the choice of a defining function determines a conformal compactification of $(M, G)$.

The metric $\tilde{G}$ induces a regular metric $g_{(0)}$ on $\partial M$. This metric depends on the defining function, as picking a different defining function Weyl rescales $g_{(0)}$. It follows that the pair $(M, G)$ determine a conformal structure (denoted $\left.\left[g_{(0)}\right]\right)$ at $\partial M$. We call $\left(\partial M,\left[g_{(0)}\right]\right)$ the conformal infinity or conformal boundary of $(M, G)$. This construction is same as the Penrose method of compactifying spacetime by introducting conformal infinity.

If we compute the Riemann tensor of $G$, we find that near $\partial M$ it has the form:

$$
\begin{equation*}
R_{\mu \nu \rho \sigma}=-\tilde{G}^{\kappa \lambda} \nabla_{\kappa} z \nabla_{\lambda} z\left(G_{\mu \rho} G_{\nu \sigma}-G_{\nu \rho} G_{\mu \sigma}\right)+O\left(z^{-3}\right) \tag{3.2}
\end{equation*}
$$

Notice that the leading term is order $z^{-4}$ as $G$ is order $z^{-2}$. Taking its trace we obtain that:

$$
\begin{equation*}
R=-D(D-1) \tilde{G}^{\kappa \lambda} \nabla_{\kappa} z \nabla_{\lambda} z+O(z) \tag{3.3}
\end{equation*}
$$

We see that for a spacetime with constant negative curvature,

$$
\begin{equation*}
R=-D(D-1) \tag{3.4}
\end{equation*}
$$

and thus we find to leading order:

$$
\begin{equation*}
\tilde{G}^{\kappa \lambda} \nabla_{\kappa} z \nabla_{\lambda} z=1 \tag{3.5}
\end{equation*}
$$

The Riemann curvature of such a metric thus approaches that of AdS space with cosmological constant $\Lambda=-(D-1)(D-2) / 2$, for which $R_{\mu \nu \rho \sigma}=-D(D-1)\left(G_{\mu \rho} G_{\nu \sigma}-G_{\nu \rho} G_{\mu \sigma}\right)$ holds exactly. A conformally compact manifold whose metric also satisfies $R=-D(D-1)$ is therefore also called an Asymptotically locally $A d S$ manifold. Notice that we added the word 'local' because we have not put any requirements on global issues like the topology of $\partial M$, which may very well be different from the sphere at conformal infinity of (Euclidean) AdS.

### 3.2 Fefferman-Graham metric

A main result of Fefferman and Graham [32] is that in a finite neighborhood of $\partial M$, the metric of an AlAdS spacetime can always be cast in the form:

$$
\begin{equation*}
d s^{2}=z^{-2}\left(d z^{2}+g_{i j} d x^{i} d x^{j}\right) \tag{3.6}
\end{equation*}
$$

[^1]where the conformal boundary is at $z=0$ and the metric $g$ is a regular metric at $\partial M$, which we can write as:
\[

$$
\begin{equation*}
g_{i j}\left(x^{k}, z\right)=g_{(0)}\left(x^{k}\right)+\ldots \tag{3.7}
\end{equation*}
$$

\]

where the dots represent terms that vanish as $z \rightarrow 0$. The coordinates in (3.6) are Gaussian normal coordinates centered at $\partial M$.

The specific form of the subleading terms, including the radial power where the first subleading terms appears, depends on the bulk theory under question and is not fixed a priori. For example, for Einstein gravity in $(d+1)$ dimensions the expansion reads

$$
\begin{equation*}
g_{i j}=g_{(0) i j}+z^{2} g_{(2) i j}+\cdots+z^{d}\left(g_{(d) i j}+h_{(d) i j} \log (z)\right)+\cdots \tag{3.8}
\end{equation*}
$$

The fact that the subleading term starts at order $z^{2}$ is specific to pure Einstein gravity. For example, $3 d$ Einstein gravity coupled to matter can have the first subleading term appearing at order $z$, see [33] for an example. The logarithmic term $h_{(d)}$ appears in Einstein gravity when $d$ is an even integer greater than 2 . This coefficient is given by the metric variation of the conformal anomaly [25]. This fact immediately explains why there is no such coefficient in Einstein gravity when $d=2$ : in this case the conformal anomaly is given by a topological invariant and therefore its variation w.r.t. the metric vanishes. As soon as the bulk action contains additional fields the expansion will be modified accordingly [25, 3335]. For example, the asymptotic solution for three dimensional Einstein gravity coupled to a free massless scalar field is of the form (3.8) with a non-zero $h_{(2)}$ coefficient, see equation (5.25) of $[25]^{3}$. Note that the $\log$ term found in [5] is precisely of this form. From this perspective the appearance of such a term in the asymptotic expansion of TMG is certainly not surprising.

What is universal in this discussion is the structure of these expansions. The subleading coefficients are determined locally in terms of $g_{(0)}$ by solving asymptotically the field equations. This procedure leads to algebraic equations that can be readily solved. On the other hand, $g_{(d)}$ is not locally determined by $g_{(0)}$ but rather by global constraints like regularity of the bulk metric in the interior of $M$. This term is related to the 1-point function of $T_{i j}$.

To repeat, according to the standard AdS/CFT dictionary the allowed subleading terms in expansions like (3.8) (and (3.9) below) are determined by the equations of motion rather than fixed by hand. As long as $g$ is regular for $z=0$ and therefore of the form (3.7), the aforementioned AlAdS properties of $(M, G)$ are unchanged. In the context of TMG this in particular implies that we allow the logarithmic mode found in [5].

### 3.3 Boundary conditions and dual sources

According to the AdS/CFT dictionary [37, 38], the coefficients of the leading terms in the radial expansion of the metric and the various matter fields are sources for corresponding gauge-invariant operators in the CFT. For example, $g_{(0)}$ specifies a boundary metric which

[^2]becomes the source for the energy-momentum tensor of the boundary theory. Similarly, a bulk scalar field $\Phi$ of mass $m$ has the allowed asymptotic behavior:
\[

$$
\begin{equation*}
\Phi=\phi_{(0)} z^{d-\Delta}+\ldots+\phi_{(2 \Delta-d)} z^{\Delta}+\ldots \tag{3.9}
\end{equation*}
$$

\]

with $m^{2}=\Delta(\Delta-d)$. We then interpret the leading term $\phi_{(0)}$ as the source for a scalar operator $\mathcal{O}$ of scaling dimension $\Delta$ dual to $\Phi$.

In field theory, one computes the partition function as a functional of sources and the same story applies in AdS/CFT. The sources like $\phi_{(0)}$ and $g_{(0)}$ determine the asymptotic (Dirichlet) values of a bulk solution to the equation of motion. The aim is now to find this bulk solution and subsequently compute its on-shell action. Since the solution of the equations of motion is a function of $\phi_{(0)}$ and $g_{(0)}$, so is the corresponding on-shell action. However, the naive action is always infinite (for example, the Einstein-Hilbert term is proportional to the volume of spacetime which always diverges for an AlAdS spacetime). We therefore need to regularize and then renormalize the computation of the on-shell action. This holographic renormalization of the on-shell action depends crucially on the asymptotic properties of the metric (which in our case is $\operatorname{AlAdS}$ ) and this is the place where the above framework finds a practical application.

Holographic renormalization is implemented as follows, see [21] for a more complete discussion. One first puts the boundary of the spacetime at finite $z_{0}$ rather than at $z=0$ and then evaluates the on-shell action for this regulated solution. One finds divergences as $z_{0} \rightarrow 0$ which can however be cancelled by adding local counterterms to the action. To maintain covariance, these counterterms should be functionals of the induced metric and other fields on the slice given by $z=z_{0}$. Adding then the counterterms to the on-shell action, one finds that the total action is finite as $z_{0} \rightarrow 0$.

Once the on-shell action is renormalized and finite, one can compute one-point functions in the presence of sources by functionally differentiating the renormalized on-shell action with respect to the sources like $g_{(0)}$ and $\phi_{(0)}$. These one-point functions involve the nonlocally determined pieces called $g_{(d) i j}$ and $\phi_{(2 \Delta-d)}$ and in general contain also local terms, some of which are related to anomalies and others that are scheme dependent. One can obtain higher-point functions by taking further derivatives of the one-point functions and the local terms lead to contact terms in $n$-point functions.

Notice that the counterterms are also necessary for the appropriate variational principle to hold: for AlAdS spacetimes one fixes $g_{(0)}$ (or rather its conformal class) instead of the induced boundary metric $g / z_{0}^{2}$ which would diverge as $z_{0} \rightarrow 0$. This is discussed in detail in [27].

### 3.4 Sources for irrelevant operators

The fact that an asymptotically AdS metric becomes that of AdS near conformal infinity is dual to the statement that the boundary theory becomes conformal at high energies. Asymptotically AdS metrics describe relevant deformations of the CFT and/or vevs in the boundary theory.

On the other hand, one may also attempt to switch on sources for irrelevant operators. Such deformations are for example necessary to compute correlation functions of irrelevant
operators, as these are obtained by functionally differentiating the on-shell action with respect to these sources. Switching on these sources spoils the conformal UV behavior of the field theory. Correspondingly, the bulk solutions will no longer be AlAdS and the usual AdS/CFT dictionary would break down. In particular, the usual counterterms no longer suffice to make the on-shell action finite, completely analogous to the nonrenormalizability of the field theory with such sources.

A consistent perturbative approach may however be set up by treating the sources for irrelevant operators as infinitesimal [25]. In the bulk, this means that one starts from an AlAdS solution and computes the bulk solution and the on-shell action to any given order $n$ in the sources. This approximation allows for the computation of $n$-point functions of the irrelevant operator in any given state dual to the background AlAdS solution. We will see a concrete example worked out below.

### 3.5 Higher-derivative terms

Higher-derivative terms in the bulk action are usually treated perturbatively and in that case do not directly lead to a change in the setup described above. However, for TMG we cannot afford to treat these terms as perturbations as we want to study the complete theory around $\mu=1$. The solution to the bulk equations of motion is then generally no longer fixed by the specification of Dirichlet data alone and some extra boundary data is needed; for example the $z$-derivatives of the metric $g_{i j}$ at the boundary. Correspondingly, the on-shell action depends on these boundary data as well. We shall see below that this is precisely what happens for TMG.

Extending the usual AdS/CFT logic, we interpret the new boundary data as a new source for another operator in the field theory. Functionally differentiating the on-shell action with respect to this new boundary data then yields correlation functions of this new operator. To make contact with earlier results, notice that for TMG this operator creates the massive graviton states in the bulk and for $\mu=1$ it creates the logarithmic solution found in [5]. One may say that these spaces have only a single operator insertion in the infinite past.

It turns out that this new operator is irrelevant for $\mu>1$, as for $\mu \geq 1$ we find that switching on the corresponding source spoils the AlAdS properties of the spacetime. Following the discussion of the previous subsection, we therefore will have to treat the source as infinitesimal and approach the problem perturbatively to a given order in the source. This is precisely what we will do in section 6.2.2.

## 4 Asymptotic analysis for $\mu=1$

In this section we return to TMG and carry out an asymptotic analysis of the equations of motion (2.4) in the Fefferman-Graham coordinate system. Note that because of (2.9) all conformally compact solutions of this theory are asymptotically locally AdS. However, not all solution of TMG are conformally compact. For example, the 'warped' solutions of [39] have a degenerate boundary metric, as is demonstrated in appendix E, and thus they are not conformally compact. In this section we restrict to the AlAdS case. We
compute the on-shell action, discuss the variational principle in detail and demonstrate how one holographically computes one-point functions in the CFT. As indicated in the previous section, we will find irrelevant operators and therefore the complete holographic renormalization of the on-shell action has to be done perturbatively. This is postponed until the next section, where we will renormalize the action to second order in the perturbations.

Although this and the next section focus on the case $\mu=1, \mu$ is sometimes reinstated for later convenience.

### 4.1 Fefferman-Graham equations of motion

Following the discussion in section 3.2, we take the metric to be of the form:

$$
\begin{equation*}
d s^{2}=\frac{d \rho^{2}}{4 \rho^{2}}+\frac{1}{\rho} g_{i j}(x, \rho) d x^{i} d x^{j} \tag{4.1}
\end{equation*}
$$

where we defined $\rho=z^{2}$. As should be clear from the previous section, this form of the metric is not an ansatz but it is a direct consequence of the AlAdS property of the spacetime. In other words, the metric of any AlAdS spacetime can be brought to this form near the conformal boundary. In this coordinate system the equations of motion (2.4) take the following form. For the component equations we find:

$$
\begin{align*}
& -\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{1}{4} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)+\frac{1}{4 \mu} \epsilon^{i j}\left(\nabla_{i} \nabla^{k} g_{k j}^{\prime}+2 \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right){ }_{j i}\right)=0, \\
& \left(\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)-\frac{1}{4}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right) g_{i j}-g_{i j}^{\prime \prime}+\frac{1}{2} g_{i j}^{\prime} \operatorname{tr}\left(g^{-1} g^{\prime}\right) \\
& +\frac{1}{\mu} \epsilon_{i}^{k}\left\{\frac{1}{4} \nabla_{k} \nabla^{m} g_{m j}^{\prime}+\frac{1}{4} \nabla_{j} \nabla^{m} g_{m k}^{\prime}-\frac{1}{2} \nabla_{k} \nabla_{j}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+2 \rho g_{j k}^{\prime \prime \prime}+\right. \\
& g_{k j}^{\prime \prime}\left[3-\frac{3}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+g_{k j}^{\prime}\left(-\frac{3}{2} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{3}{4} \rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right. \\
& \left.\left.-\frac{7}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{7}{4} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right)\right\}+i \leftrightarrow j=0, \\
& \left(g^{k j}-\mu \epsilon^{k j}\right) \nabla_{k} g_{i j}^{\prime}-\nabla_{i}\left(\operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{1}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)-\rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right) \\
& +2 \rho \nabla^{n}\left(g_{i n}^{\prime \prime}-\operatorname{tr}\left(g^{-1} g^{\prime}\right) g_{i n}^{\prime}\right)+\rho\left(g^{-1} g^{\prime}\right){ }_{i}^{k} \nabla^{l} g_{k l}^{\prime}=0, \tag{4.2}
\end{align*}
$$

whereas the trace equation $R=-6$ becomes:

$$
\begin{equation*}
-4 \rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+3 \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)-\rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}+R(g)+2 \operatorname{tr}\left(g^{-1} g^{\prime}\right)=0 . \tag{4.3}
\end{equation*}
$$

A prime denotes a derivative with respect to $\rho$. The derivation of these equations is given in appendix A .

### 4.2 Asymptotic solution

Rather than the usual asymptotic behavior $\lim _{\rho \rightarrow 0} g_{i j}\left(\rho, x^{k}\right)=g_{(0) i j}\left(x^{k}\right)$, the equations of motion for $\mu=1$ also allow leading log asymptotics for $g_{i j}$. We therefore substitute the
expansion

$$
\begin{equation*}
g_{i j}=b_{(0) i j} \log (\rho)+g_{(0) i j}+b_{(2) i j} \rho \log (\rho)+g_{(2) i j}+\ldots \tag{4.4}
\end{equation*}
$$

into the equations of motion. The subleading logarithmic term $b_{(2) i j}$ in this expansion is the mode considered in [5]. The leading logarithmic term $b_{(0) i j}$, on the other hand, changes the asymptotic structure of the spacetime and it is no longer AlAdS. Following the discussion in section 3.4 , we will treat $b_{(0) i j}$ to be infinitesimal and work perturbatively in $b_{(0) i j}$. As we will be interested in two-point functions around a background with $b_{(0) i j}=0$, it suffices to retain only terms linear in $b_{(0) i j}$ in the equations that follow.

Under these conditions we find:

$$
\begin{align*}
g_{i j}^{\prime} & =\frac{b_{(0) i j}}{\rho}+b_{(2) i j} \log (\rho)+b_{(2) i j}+g_{(2) i j}+\ldots, \\
g_{i j}^{\prime \prime} & =-\frac{b_{(0) i j}}{\rho^{2}}+\frac{b_{(2) i j}}{\rho}+\ldots,  \tag{4.5}\\
g_{i j}^{\prime \prime \prime} & =\frac{2 b_{(0) i j}}{\rho^{3}}-\frac{b_{(2) i j}}{\rho^{2}}+\ldots, \\
g^{i j} & =g_{(0)}^{i j}-b_{(0)}^{i j} \log (\rho)-b_{(2)}^{i j} \rho \log (\rho)-\rho g_{(2)}^{i j}+\mathcal{O}\left(b_{(0)}\right)+\ldots,
\end{align*}
$$

where in the last line indices are raised with $g_{(0)}$ and the $\mathcal{O}\left(b_{(0)}\right)$ terms are of the form $b_{(2) k}^{i} b_{(0)}^{k j} \rho \log ^{2}(\rho)+g_{(2) k}^{i} b_{(0)}^{k j} \rho \log (\rho)$, but will never be needed in what follows.

Substituting this expansion in the equations of motion (4.2) and (4.3), we find the following. To leading order we find both from the $(\rho \rho)$ equation as well as from the $R$ equation that:

$$
\begin{equation*}
\operatorname{tr}\left(b_{(0)}\right)=0 \tag{4.6}
\end{equation*}
$$

Notice that traces are now implicitly taken using $g_{(0)}$, that is $\operatorname{tr}\left(b_{(0)}\right) \equiv g_{(0)}^{i j} b_{(0) i j}$. Also, in this subsection the $\epsilon$-symbol and covariant derivatives are defined using $g_{(0)}$. From the $(i j)$ equation we find that:

$$
\begin{equation*}
P_{i}^{k} b_{(0) k j}=0 \tag{4.7}
\end{equation*}
$$

where we define the projection operators:

$$
\begin{equation*}
P_{i}^{k} \equiv \frac{1}{2}\left(\delta_{i}^{k}+\epsilon_{i}^{k}\right), \quad \quad \bar{P}_{i}^{k} \equiv \frac{1}{2}\left(\delta_{i}^{k}-\epsilon_{i}^{k}\right), \tag{4.8}
\end{equation*}
$$

and we obtain no new constraint from the ( $\rho i$ ) equation at leading order.
At subleading order we encounter various $\log$ terms. From the $R$ equation we find at order $\log ^{2}(\rho)$ that

$$
\begin{equation*}
\operatorname{tr}\left(b_{(2)} g_{(0)}^{-1} b_{(0)}\right)=0 \tag{4.9}
\end{equation*}
$$

and at order $\log (\rho)$ we then find:

$$
\begin{equation*}
-2 \operatorname{tr}\left(b_{(0)} g_{(0)}^{-1} g_{(2)}\right)+2 \operatorname{tr}\left(b_{(2)}\right)+\tilde{R}\left[b_{(0)}\right]=0 \tag{4.10}
\end{equation*}
$$

with $\tilde{R}\left[b_{(0)}\right]$ the linearized curvature:

$$
\begin{equation*}
R[g]=R\left[g_{(0)}\right]+\log (\rho) \tilde{R}\left[b_{(0)}\right]+\ldots \tag{4.11}
\end{equation*}
$$

which can be more explicitly written as:

$$
\begin{equation*}
\tilde{R}\left[b_{(0)}\right]=\nabla^{i} \nabla^{j} b_{(0) i j}, \tag{4.12}
\end{equation*}
$$

where we used the properties of $b_{(0) i j}$ found at leading order. At subleading order in the $(\rho \rho)$ equation we again obtain (4.9) and (4.10). At order one in the $R$ equation we obtain:

$$
\begin{equation*}
-2 \operatorname{tr}\left(b_{(2)}\right)+2 \operatorname{tr}\left(g_{(2)}\right)+R\left[g_{(0)}\right]=0 \tag{4.13}
\end{equation*}
$$

For the ( $i j$ ) equation the subleading terms at order $\log (\rho) / \rho$ give

$$
\begin{equation*}
\left(b_{(0)} g_{(0)}^{-1} b_{(2)}\right)_{i j}+\left(b_{(2)} g_{(0)}^{-1} b_{(0)}\right)_{i j}=0, \tag{4.14}
\end{equation*}
$$

and at order $1 / \rho$ we obtain:

$$
\begin{equation*}
\bar{P}_{i}^{k} b_{(2) k j}=\frac{1}{2}\left(b_{(2) i j}-\epsilon_{i}^{k} b_{(2) k j}\right)=\mathcal{O}\left(b_{(0) i j}\right), \tag{4.15}
\end{equation*}
$$

where the right-hand side is an expression linear in $b_{(0) i j}$ that we will not need below.
For the ( $\rho i$ ) equation, we find at subleading order that:

$$
\begin{equation*}
\bar{P}_{i}^{k}\left(\nabla^{j} g_{(2) j k}+\frac{1}{2} \nabla_{k} R\left[g_{(0)}\right]\right)=\nabla^{l} b_{(2) l i}+\mathcal{O}\left(b_{(0)}\right) . \tag{4.16}
\end{equation*}
$$

We may apply (4.15) to rewrite schematically $b_{(2) i j} \rightarrow P_{i}^{k} b_{(2) k j}+\mathcal{O}\left(b_{(0)}\right)$. Since $P_{i}^{k}$ and $\bar{P}_{i}^{k}$ are projection operators onto orthogonal subspaces we can split this equation into:

$$
\begin{equation*}
\bar{P}_{i}^{k}\left(\nabla^{j} g_{(2) j k}+\frac{1}{2} \nabla_{k} R\left[g_{(0)}\right]\right)=\mathcal{O}\left(b_{(0)}\right), \quad \quad \nabla^{l} b_{(2) l i}=\mathcal{O}\left(b_{(0)}\right) . \tag{4.17}
\end{equation*}
$$

If $b_{(0) i j}=0$ then the first of these equations agrees with [40].

### 4.3 On-shell action

In this section we will write the on-shell action in Fefferman-Graham coordinates and analyze the divergences obtained by substituting the expansion (4.4).

We begin by computing the on-shell value of the Chern-Simons part of the action,

$$
\begin{equation*}
I_{\mathrm{cs}}=\frac{1}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{-G} \epsilon^{\lambda \mu \nu}\left(\Gamma_{\lambda \sigma}^{\rho} \partial_{\mu} \Gamma_{\rho \nu}^{\sigma}+\frac{2}{3} \Gamma_{\lambda \sigma}^{\rho} \Gamma_{\mu \tau}^{\sigma} \Gamma_{\nu \rho}^{\tau}\right), \tag{4.18}
\end{equation*}
$$

in Fefferman-Graham coordinates. Observing that the $\epsilon$-symbol implies that only one of the indices $\lambda, \mu$ or $\nu$ can be the radial direction, we can directly write out the various terms. Using then (A.2) and (A.4) from appendix A we find that many terms cancel due to the antisymmetry of $\epsilon^{i j}$ and we are left with:

$$
\begin{equation*}
\frac{1}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{-g} \epsilon^{i j}\left(2 \rho\left(g^{\prime} g^{-1} g^{\prime \prime}\right)_{i j}-\Gamma_{i b}^{a} \partial_{\rho} \Gamma_{a j}^{b}\right) \tag{4.19}
\end{equation*}
$$

where the connection coefficients and $\epsilon$ tensor are now those associated with $g_{i j}$. Substituting (4.4), it is not hard to verify that this action is finite for $\rho_{0} \rightarrow 0$ if $b_{(0)}{ }_{i j}=0$, but there are log divergences if $b_{(0) i j}$ is nonzero.

For the Einstein-Hilbert action, the variational principle can be made well-defined for Dirichlet boundary conditions at a finite radial distance by the addition of the GibbonsHawking term. In our conventions, this means that the Einstein part of the action is given by:

$$
\begin{equation*}
I_{\mathrm{gr}}=\frac{1}{16 \pi G_{N}} \int d^{3} x \sqrt{-G}(R-2 \Lambda)+\frac{1}{8 \pi G_{N}} \int d^{2} x \sqrt{-\gamma} K \tag{4.20}
\end{equation*}
$$

where $\gamma_{i j}=g_{i j} / \rho$ is the induced metric on the cutoff surface $\rho=\rho_{0}$, which is kept fixed in the variational problem. Furthermore, $K$ is the trace of the extrinsic curvature of this surface, which is defined using the outward pointing unit normal $n_{\mu} d x^{\mu}=-d \rho /(2 \rho)$.

This variational problem becomes ill-posed as $\rho_{0} \rightarrow 0$, since the induced metric $\gamma$ diverges in this limit. What one should instead keep fixed is the conformal class of $\gamma$ (or $g_{(0)}$ after taking into account the issues related to the conformal anomaly) [27]. This requires introducing additional boundary terms. These boundary terms not only make the variational problem well-posed but also make the on-shell action finite as $\rho_{0} \rightarrow 0$. In particular, for the pure Einstein theory the counterterm action is

$$
\begin{equation*}
I_{\mathrm{ct}}=\frac{1}{8 \pi G_{N}} \int d^{2} x \sqrt{-\gamma}\left(-1+\frac{1}{4} R[\gamma] \log \left(\rho_{0}\right)\right) . \tag{4.21}
\end{equation*}
$$

Substituting the Fefferman-Graham form of the metric we find:

$$
\begin{align*}
& I_{\mathrm{gr}}=-\frac{1}{16 \pi G_{N}} \int d^{3} x \frac{2}{\rho^{2}} \sqrt{-g}+\frac{1}{16 \pi G_{N}} \int d^{2} x \frac{1}{\rho} \sqrt{-g}\left(4-2 \rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right), \\
& I_{\mathrm{ct}}=\frac{1}{8 \pi G_{N}} \int d^{2} x \sqrt{-g}\left(-\frac{1}{\rho_{0}}+\frac{1}{4} R[g] \log \left(\rho_{0}\right)\right) . \tag{4.22}
\end{align*}
$$

We may now substitute the radial expansion (4.4) for $g_{i j}$ and find the same behavior as for the Chern-Simons part: the action $I_{\mathrm{gr}}+I_{\mathrm{ct}}$ is finite when $b_{(0) i j}=0$ but diverges otherwise.

We now define the following combined action:

$$
\begin{equation*}
I_{\mathrm{c}}=I_{\mathrm{gr}}+I_{\mathrm{cs}}+I_{\mathrm{ct}}, \tag{4.23}
\end{equation*}
$$

which we emphasize is finite only as long as $b_{(0) i j}$ vanishes and needs to be supplemented with additional boundary counterterms otherwise. As we explained in section 3 , this will be done perturbatively up to the required order in $b_{(0) i j}$. We will do an explicit analysis to second order in section 6 , but first we discuss the variational principle and the computation of the one-point functions in general terms.

### 4.3.1 Variational principle

In this subsection we compute the variation of the combined action $I_{c}$ defined in (4.23), which will be needed below in the holographic computation of boundary correlation functions.

First of all, the variation of the Einstein-Hilbert action plus Gibbons-Hawking term is well-known:

$$
\begin{equation*}
\delta I_{\mathrm{gr}}=\int d^{3} x(\mathrm{eom})+\frac{1}{16 \pi G_{N}} \int d^{2} x \sqrt{-\gamma}\left[\gamma^{i j} K-K^{i j}\right] \delta \gamma_{i j}, \tag{4.24}
\end{equation*}
$$

and in Fefferman-Graham coordinates we find that:

$$
\begin{align*}
\delta I_{\mathrm{gr}} & =\int d^{3} x(\mathrm{eom})+\frac{1}{16 \pi G_{N}} \int d^{2} x \sqrt{-g}\left(\frac{1}{\rho} g^{i j}+g^{i j}-g^{i j} \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right) \delta g_{i j}  \tag{4.25}\\
\delta I_{\mathrm{ct}} & =-\frac{1}{16 \pi G_{N}} \frac{1}{\rho} \int d^{2} x \sqrt{-g} g^{i j} \delta g_{i j}
\end{align*}
$$

As for the Chern-Simons part, we find that

$$
\begin{equation*}
\delta I_{\mathrm{cs}}=\frac{1}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{-G} \epsilon^{\lambda \mu \nu} C_{\lambda \sigma}^{\rho} R_{\nu \mu \rho}^{\sigma}+\frac{1}{32 \pi G_{N} \mu} \int d^{2} x \sqrt{-\gamma} \epsilon^{\lambda \mu \nu} n_{\mu} \Gamma_{\lambda \sigma}^{\rho} C_{\nu \rho}^{\sigma} \tag{4.26}
\end{equation*}
$$

with

$$
\begin{equation*}
C_{\mu \nu}^{\lambda}=\delta \Gamma_{\mu \nu}^{\lambda}=\frac{1}{2} G^{\lambda \sigma}\left(\nabla_{\mu} \delta G_{\nu \sigma}+\nabla_{\nu} \delta G_{\mu \sigma}-\nabla_{\sigma} \delta G_{\mu \nu}\right) \tag{4.27}
\end{equation*}
$$

and $n_{\mu}$ the outward pointing unit normal to the boundary and $\gamma_{i j}$ the induced metric on the boundary. Integrating the bulk part once more by parts, we find:

$$
\begin{align*}
\delta I_{\mathrm{CS}}= & -\frac{1}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{-G} \epsilon^{\lambda \mu \nu}\left(\nabla_{\sigma} R_{\nu \mu}{ }^{\rho \sigma}\right) \delta G_{\lambda \rho}  \tag{4.28}\\
& +\frac{1}{32 \pi G_{N} \mu} \int d^{2} x \sqrt{-\gamma} \epsilon^{\lambda \mu \nu}\left(n_{\mu} \Gamma_{\lambda \sigma}^{\rho} C_{\nu \rho}^{\sigma}+n_{\sigma} R_{\nu \mu}{ }^{\rho \sigma} \delta G_{\lambda \rho}\right)
\end{align*}
$$

The first term eventually becomes the Cotton tensor in the equation of motion, using (2.3) and the Bianchi identity.

Substituting now once more the Fefferman-Graham metric (4.1), we find $n_{\mu} d x^{\mu}=$ $-d \rho /(2 \rho)$ and the surface terms can be rewritten to yield:

$$
\begin{gather*}
\delta I_{\mathrm{CS}}=\int d^{3} x(\mathrm{eom})+\frac{1}{16 \pi G_{N} \mu} \int d^{2} x \sqrt{-g} \epsilon^{i j}\left(\frac{1}{2} \Gamma_{i k}^{l} \delta \Gamma_{j l}^{k}+\left(g^{\prime} g^{-1} \delta g\right)_{i j}-\rho\left(g^{\prime} g^{-1} \delta g^{\prime}\right)_{i j}\right. \\
\left.+2 \rho\left(g^{\prime \prime} g^{-1} \delta g\right)_{i j}-\rho\left(g^{\prime} g^{-1} g^{\prime} g^{-1} \delta g\right)_{i j}\right) \tag{4.29}
\end{gather*}
$$

with all covariant terms defined using $g_{i j}$. Notice that if $b_{(0) i j}=0$ then all terms are finite in the limit where the radial cutoff $\rho_{0} \rightarrow 0$, in agreement with the above analysis for the on-shell action.

Combining then (4.25) and (4.29), the variation of the combined action $I_{\mathrm{c}}$ defined in (4.23) is:

$$
\begin{align*}
\delta I_{\mathrm{c}}= & \frac{1}{16 \pi G_{N}} \int d^{2} x \sqrt{-g}\left\{g_{i j}^{\prime}-g_{i j} \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right\}\left(g^{-1}(\delta g) g^{-1}\right)^{i j}  \tag{4.30}\\
& +\frac{1}{16 \pi G_{N} \mu} \int d^{2} x \sqrt{-g}\left\{\frac{1}{2} A_{i j}-2 \rho \epsilon_{i}^{k}\left[g_{k j}^{\prime \prime}-\frac{1}{2}\left(g^{\prime} g^{-1} g^{\prime}\right)_{k j}\right]-\epsilon_{i}^{k} g_{k j}^{\prime}\right\}\left(g^{-1}(\delta g) g^{-1}\right)^{i j} \\
& +\frac{1}{16 \pi G_{N} \mu} \int d^{2} x \sqrt{-g} \rho \epsilon_{i}^{k} g_{k j}^{\prime}\left(g^{-1}\left(\delta g^{\prime}\right) g^{-1}\right)^{i j} .
\end{align*}
$$

where the term $A_{i j}$ is a local term and is defined via:

$$
\begin{equation*}
\int d^{2} x \sqrt{-g} \epsilon^{i j} \Gamma_{i k}^{l} \delta \Gamma_{j l}^{k}=\int d^{2} x \sqrt{-g} A^{i j} \delta g_{i j} \tag{4.31}
\end{equation*}
$$

Explicitly, we find:

$$
\begin{align*}
A_{i j} & =\frac{1}{4}\left[\epsilon^{k l} g_{i}^{m} g_{j n}+\epsilon_{i}^{l} g_{j}^{m} g_{n}^{k}-\epsilon_{j}^{l} g^{m k} g_{i n}+(i \leftrightarrow j)\right] \nabla_{k} \Gamma_{l m}^{n} \\
& =\left[-\frac{1}{8} \epsilon_{i}^{k} \epsilon_{j}^{l} \epsilon^{m n} \nabla_{l} \partial_{m} g_{n k}+(i \leftrightarrow j)\right]+\frac{1}{4} \epsilon^{k l} \nabla_{k} \partial_{l} g_{i j} . \tag{4.32}
\end{align*}
$$

Notice that the last term in (4.30) involves $\delta g_{i j}^{\prime}$ and therefore changes the variational principle for this action. Although one may explicitly check that it vanishes if $b_{(0) i j}=0$ and for $\rho_{0} \rightarrow 0$ [41], this is no longer the case for nonzero $b_{(0) i j}$. As expected for a threederivative bulk action, the on-shell action is a functional of both $g_{i j}$ and $g_{i j}^{\prime}$ at the boundary and we can take functional derivatives with respect to both of them.

### 4.4 One-point functions

From the previous section it follows that there are two independent sources that should be specified at the conformal boundary, which are asymptotically related to $g_{i j}$ and $g_{i j}^{\prime}$. According to the asymptotic solution (4.4) obtained in section 4.2 we can indeed independently specify both $b_{(0) i j}$ and $g_{(0) i j}$ and one can take these as the two boundary sources. These fields then source two operators which will be denoted $t_{i j}$ and $T_{i j}$, respectively, with $T_{i j}$ the usual energy-momentum tensor of the boundary theory. The standard AdS/CFT dictionary now dictates:

$$
\begin{equation*}
\left\langle T_{i j}\right\rangle=\frac{-4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta I}{\delta g_{(0)}^{i j}}, \quad\left\langle t_{i j}\right\rangle=\left(\frac{-4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta I}{\delta b_{(0)}^{i j}}\right)_{L} \tag{4.33}
\end{equation*}
$$

where the subscript 'L' means a projection onto the chiral traceless component,

$$
\begin{equation*}
\left(t_{i j}\right)_{L} \equiv P_{i}^{k}\left(t_{k j}-\frac{1}{2} g_{k j} \operatorname{tr}(t)\right) \tag{4.34}
\end{equation*}
$$

whose origin is explained in the next paragraph. The signs in (4.33) are explained in appendix B. Notice that the on-shell action $I$ on the right-hand sides of (4.33) coincides with $I_{\mathrm{c}}$ defined in (4.23) only to zeroth order in $b_{(0) i j}$, and as explained above additional boundary counterterms will be needed to render it finite to higher orders in $b_{(0) i j}$.

The projection onto the 'L' component originates as follows. Since $P_{i}^{k} b_{(0) k j}=\operatorname{tr}\left(b_{(0)}\right)=$ $0, b_{(0) i j}$ has only a single nonvanishing component. We can therefore only take functional derivatives with respect to this component and we find that $t_{i j}$ only has one component as well. For example, when we use lightcone coordinates and the boundary metric is flat, $g_{(0) i j} d x^{i} d x^{j}=d u d v$, then in our conventions (see appendix B) only $b_{(0) u u}$ is nonzero. Correspondingly, the only non-zero component of $t_{i j}$ is $t_{v v}$ and taking the 'L' piece projects onto this component.

To make contact with the regulated on-shell action which explicitly depends on $g_{i j}$ and $g_{i j}^{\prime}$, we observe that:

$$
\begin{equation*}
g_{(0)}^{i j}=\lim _{\rho \rightarrow 0}\left(g^{i j}+\rho \log (\rho) g^{i j}\right), \quad \quad b_{(0) i j}=\lim _{\rho \rightarrow 0} \rho g^{\prime i j} \tag{4.35}
\end{equation*}
$$

and therefore the one-point functions can be obtained concretely by computing:

$$
\begin{align*}
& \left\langle t_{i j}\right\rangle=\lim _{\rho \rightarrow 0}\left(\frac{-4 \pi}{\rho \sqrt{-g}} \frac{\delta I}{\delta g^{\prime i j}}+\log (\rho) \frac{4 \pi}{\sqrt{-g}} \frac{\delta I}{\delta g^{i j}}\right)_{L},  \tag{4.36}\\
& \left\langle T_{i j}\right\rangle=\lim _{\rho \rightarrow 0} \frac{-4 \pi}{\sqrt{-g}} \frac{\delta I}{\delta g^{i j}},
\end{align*}
$$

which are the main expressions that will be used in the following sections.

### 4.4.1 Explicit expressions for vanishing $b_{(0) i j}$

If we set $b_{(0)}{ }_{i j}=0$ then the combined action $I_{\mathrm{c}}$ is finite on-shell. Although we then cannot take functional derivatives with respect to $b_{(0)}{ }_{i j}$, we can still compute correlation functions involving the energy-momentum tensor by using the first equation in (4.33) with $I=I_{\mathrm{c}}$. Explicitly, this means that we use (4.30) and substitute the expansion (4.4) with $b_{(0) i j}=0$. This leads to the following one-point functions:

$$
\begin{align*}
\left\langle T_{i j}\right\rangle & \equiv \lim _{\rho \rightarrow 0} \frac{-4 \pi}{\sqrt{-g}} \frac{\delta I_{\mathrm{c}}}{\delta g^{i j}}  \tag{4.37}\\
& =\frac{1}{4 G_{N}}\left(g_{i j}^{\prime}-g_{i j} \operatorname{tr}\left(g^{-1} g^{\prime}\right)-\frac{1}{\mu}\left(\frac{1}{2} \epsilon_{i}^{k} g_{k j}^{\prime}+\rho \epsilon_{i}^{k} g_{k j}^{\prime \prime}+(i \leftrightarrow j)\right)+\frac{1}{2 \mu} A_{i j}\left[g_{i j}\right]\right) \\
& =\frac{1}{4 G_{N}}\left(g_{(2) i j}+\frac{1}{2} R\left[g_{(0)}\right] g_{(0) i j}-\frac{1}{2 \mu}\left(\epsilon_{i}^{k} g_{(2) k j}+(i \leftrightarrow j)\right)-\frac{2}{\mu} b_{(2) i j}+\frac{1}{2 \mu} A_{i j}\left[g_{(0) i j}\right]\right)
\end{align*}
$$

where we defined $\epsilon_{i}{ }^{k}$ using $g_{(0)}$ and also used the various properties of $b_{(2) i j}$ found above, in particular the condition $\epsilon_{i}{ }^{k} b_{(2) k j}=b_{(2) i j}$ which ensured the absence of a logarithmic divergence. Notice that an extra sign arises because we functionally differentiate with respect to the inverse metric, whereas $(4.30)$ uses a variation in the metric itself. The expression with energy momentum tensor with $b_{(0) i j}=b_{(2) i j}=0$ was also derived previously in [41]. The authors of [5] computed $T_{i j}$ for non-zero $b_{(2) i j}$ and flat $g_{(0)}$. The result in equation (48) of [5] however is missing the $b_{(2)}$ term.

Using $g_{(0)}$ to raise indices and define covariant derivatives and using the above properties of $b_{(2) i j}$ and $g_{(2) i j}$, we find the following Ward identities:

$$
\begin{align*}
\left\langle T_{i}^{i}\right\rangle & =\frac{1}{4 G_{N}}\left(\frac{1}{2} R\left[g_{(0)}\right]+\frac{1}{2 \mu} A_{i}^{i}\left[g_{(0)}\right]\right), \\
\nabla^{j}\left\langle T_{i j}\right\rangle & =\frac{1}{4 \mu G_{N}}\left(\frac{1}{4} \epsilon_{i j} \nabla^{j} R\left[g_{(0)}\right]+\frac{1}{2} \nabla^{j} A_{i j}\left[g_{(0)}\right]\right) . \tag{4.38}
\end{align*}
$$

These results agree with analogous computations in [25, 40]. We will discuss their interpretation in the next section.

Example: conserved charges for the BTZ black hole. The holographic energy momentum can be used to compute the conserved charges, namely the mass and the angular momentum, for the rotating BTZ black hole. The metric can be written in Fefferman-

Graham coordinates as:

$$
\begin{align*}
d s^{2}= & \frac{d \rho^{2}}{4 \rho^{2}}-\left[\frac{1}{\rho}-\frac{1}{2}\left(r_{+}^{2}+r_{-}^{2}\right)+\frac{1}{4}\left(r_{+}^{2}-r_{-}^{2}\right)^{2} \rho\right] d t^{2}  \tag{4.39}\\
& +\left[\frac{1}{\rho}+\frac{1}{2}\left(r_{+}^{2}+r_{-}^{2}\right)+\frac{1}{4}\left(r_{+}^{2}-r_{-}^{2}\right)^{2} \rho\right] d \phi^{2}+2 r_{+} r_{-} d t d \phi
\end{align*}
$$

from which we find the following one-point function (using $\epsilon_{t \phi}=-1$ ):

$$
\begin{align*}
\left\langle T_{t t}\right\rangle & =\left\langle T_{\phi \phi}\right\rangle=\frac{1}{8 G_{N}}\left(r_{+}^{2}+r_{-}^{2}+\frac{2}{\mu} r_{+} r_{-}\right)  \tag{4.40}\\
\left\langle T_{t \phi}\right\rangle & =\frac{1}{8 G_{N}}\left(2 r_{+} r_{-}+\frac{1}{\mu} r_{+}^{2}+r_{-}^{2}\right)
\end{align*}
$$

Notice that our normalization of the energy-momentum tensor differs by a factor of $2 \pi$ from that used in much of the AdS/CFT literature. We obtain the conserved charges:

$$
\begin{align*}
M & =-\int d \phi T_{t}^{t}
\end{align*}=\frac{\pi}{4 G_{N}}\left[r_{+}^{2}+r_{-}^{2}+\frac{2}{\mu} r_{+} r_{-}\right], ~ 又 d \phi T_{\phi}^{t}=\frac{\pi}{4 G_{N}}\left[2 r_{+} r_{-}+\frac{1}{\mu}\left(r_{+}^{2}+r_{-}^{2}\right)\right] .
$$

Up to the change in the overall normalization, these expressions agree with [41, 42] and in the Einstein case $\mu \rightarrow \infty$ they reduce to the usual expressions. In lightcone coordinates $u=t+\phi, v=-t+\phi$ we find that

$$
\begin{align*}
\left\langle T_{u u}\right\rangle & =\frac{1}{G_{N}}\left(\left(1+\frac{1}{\mu}\right)\left(r_{+}^{2}+r_{-}^{2}\right)+2\left(\frac{1}{\mu}+1\right) r_{+} r_{-}\right)  \tag{4.42}\\
\left\langle T_{v v}\right\rangle & =\frac{1}{G_{N}}\left(\left(1-\frac{1}{\mu}\right)\left(r_{+}^{2}+r_{-}^{2}\right)+2\left(\frac{1}{\mu}-1\right) r_{+} r_{-}\right)
\end{align*}
$$

so when $\mu=1$ only $T_{u u}$ is nonzero.

## 5 Anomalies

In this section we will discuss and interpret the anomalous Ward identities (4.38). We will first consider the diffeomorphism anomaly and show that it agrees exactly with the expression expected from Wess-Zumino consistency conditions. We then discuss the Weyl anomaly and again find agreement with field theory expectations.

### 5.1 Diffeomorphism anomaly

The diffeomorphism Ward identity from (4.38) for $\mu=1$ reads

$$
\begin{equation*}
\nabla^{j}\left\langle T_{i j}\right\rangle=\frac{1}{4 G_{N}}\left(\frac{1}{4} \epsilon_{i}^{k} \nabla_{k} R\left[g_{(0)}\right]+\frac{1}{2} \nabla^{j} A_{i j}\left[g_{(0)}\right]\right) \tag{5.1}
\end{equation*}
$$

The right-hand side is the diffeomorphism anomaly of the theory. A more explicit expression can be obtained following [43]. Consider a vector field $\zeta^{i}$. Then, under a diffeomorphism along $\zeta^{i}$ the metric change $\delta g_{i j}=\nabla_{i} \zeta_{j}+\nabla_{j} \zeta_{i}$ results in the following change in the connection coefficients:

$$
\begin{equation*}
\delta \Gamma_{i j}^{k}=\zeta^{m} \partial_{m} \Gamma_{i j}^{k}+\left(\partial_{i} \zeta^{m}\right) \Gamma_{m j}^{k}+\left(\partial_{j} \zeta^{m}\right) \Gamma_{i m}^{k}-\Gamma_{i j}^{m} \partial_{m} \zeta^{k}+\partial_{i} \partial_{j} \zeta^{k} \tag{5.2}
\end{equation*}
$$

We may substitute this in (4.31) and find that:

$$
\begin{align*}
& -2 \int d^{2} x \sqrt{-g} \zeta_{j} \nabla_{i} A^{i j} \\
& \quad=\int d^{2} x \sqrt{-g} \epsilon^{i j} \Gamma_{i k}^{l}\left(\zeta^{m} \partial_{m} \Gamma_{j l}^{k}+\left(\partial_{j} \zeta^{m}\right) \Gamma_{m l}^{k}+\left(\partial_{l} \zeta^{m}\right) \Gamma_{j m}^{k}-\Gamma_{j l}^{m} \partial_{m} \zeta^{k}+\partial_{j} \partial_{l} \zeta^{k}\right) \\
& \quad=\int d^{2} x \sqrt{-g}\left(-\zeta^{m} \Gamma_{m j}^{i} R \epsilon_{i}^{j}-\left(\partial_{j} \zeta^{i}\right) R \epsilon_{i}^{j}-\left(\partial_{j} \zeta^{i}\right) \epsilon^{k l} \partial_{k} \Gamma_{l i}^{j}\right)  \tag{5.3}\\
& \quad=\int d^{2} x \sqrt{-g} \zeta^{i}\left(\epsilon_{i}^{j} \nabla_{j} R+\epsilon^{k l} \partial_{j} \partial_{k} \Gamma_{l i}^{j}\right)
\end{align*}
$$

where the first term on the third line comes from the grouping the first two terms on the second line; to find it we used that $\epsilon^{k l} \Gamma_{k i}^{j} \Gamma_{l j}^{n} \Gamma_{m n}^{i}=0$ in two dimensions. Substituting the explicit expression for $\nabla^{i} A_{i j}$ obtained from (5.3) in (5.1) we obtain:

$$
\begin{equation*}
\nabla^{j}\left\langle T_{i j}\right\rangle=\frac{-1}{16 G_{N}} \epsilon^{k l} \partial_{j} \partial_{k} \Gamma_{l i}^{j} . \tag{5.4}
\end{equation*}
$$

As explained in [43, 44], this is precisely the two-dimensional diffeomorphism anomaly that satisfies the Wess-Zumino consistency conditions. In particular, in this case the consistency condition requires that the anomaly under a diffeomorphism along $\zeta$ :

$$
\begin{equation*}
H_{\zeta}=\int d^{2} x \sqrt{-g} \zeta^{i} \nabla^{j}\left\langle T_{i j}\right\rangle, \tag{5.5}
\end{equation*}
$$

satisfies

$$
\begin{equation*}
E_{\zeta_{1}} H_{\zeta_{2}}-E_{\zeta_{2}} H_{\zeta_{1}}=H_{\left[\zeta_{2}, \zeta_{1}\right]}, \tag{5.6}
\end{equation*}
$$

where $E_{\zeta}$ denotes the action of a diffeomorphism with parameter $\zeta$.
The consistent anomaly (5.4) is not covariant [43, 44] and therefore $T_{i j}$ itself is not a covariant tensor either. One may try to remedy this by finding a symmetric local 'improvement term' $Y_{i j}$ such that the new object $\hat{T}_{i j}$ defined as:

$$
\begin{equation*}
\hat{T}_{i j}=T_{i j}+Y_{i j} \tag{5.7}
\end{equation*}
$$

does transform as a tensor. This implies that $\nabla^{i} \hat{T}_{i j}$ is also covariant, resulting in a covariant diffeomorphism anomaly [43]. The covariant anomaly does not however satisfy the consistency conditions [44] and therefore $\hat{T}_{i j}$ is not the variation of an effective action.

To better understand the form (5.1) of the diffeomorphism anomaly, we will now review the results summarized in [43]. ${ }^{4}$ As we will see shortly, one may obtain the covariant and the consistent anomaly as well as the improvement term starting from a single polynomial $P(\boldsymbol{\Omega})$ of degree $d / 2+1$ whose arguments are matrix-valued forms $\boldsymbol{\Omega}$. (In this section such

[^3]forms are always written using bold face.) Although $P$ generally depends on the theory at hand, in $d=2$ we find that $P$ should be quadratic, leaving us with the unique possibility:
\[

$$
\begin{equation*}
P(\boldsymbol{\Omega})=a \operatorname{Tr}(\boldsymbol{\Omega} \wedge \boldsymbol{\Omega}) \tag{5.8}
\end{equation*}
$$

\]

with a so far arbitrary normalization factor $a$. We will also write $P\left(\boldsymbol{\Omega}_{\mathbf{1}}, \boldsymbol{\Omega}_{\mathbf{2}}\right)=a \operatorname{Tr}\left(\boldsymbol{\Omega}_{\mathbf{1}} \wedge\right.$ $\boldsymbol{\Omega}_{\mathbf{2}}$ ). Following the usual conventions [43, 44], we view the connection coefficients $\Gamma_{i j}^{k}$ as matrix-valued one-forms,

$$
\begin{equation*}
\boldsymbol{\Gamma} \equiv \Gamma_{j}^{k}=\Gamma_{i j}^{k} d x^{i} \tag{5.9}
\end{equation*}
$$

and the Riemann tensor as a matrix-valued two-form,

$$
\begin{equation*}
\mathbf{R} \equiv R_{k}^{l}=\frac{1}{2} R_{i j k}^{l} d x^{i} \wedge d x^{j} \tag{5.10}
\end{equation*}
$$

The consistent anomaly can be found by solving a set of descent equations which follow from the consistency condition, see [43]. Using a matrix-valued zero-form $\mathbf{v}=v_{i}^{j}=\partial_{i} \zeta^{j}$, the end result can be written as:

$$
\begin{equation*}
H_{\zeta} \equiv \int d^{2} x \sqrt{-g} \zeta_{i} \nabla_{j} T^{i j}=\int P(d \mathbf{v}, \boldsymbol{\Gamma}) \tag{5.11}
\end{equation*}
$$

With the above form of $P$ this can be written more explicitly as:

$$
\begin{align*}
\int d^{2} x \sqrt{-g} \zeta_{i} \nabla_{j} T^{i j} & =-a \int \operatorname{Tr}(d \mathbf{v} \wedge \boldsymbol{\Gamma}) \\
& =-a \int\left(\partial_{k} \partial_{i} \zeta^{j}\right) \Gamma_{l j}^{i} d x^{k} \wedge d x^{l}=-a \int d^{2} x \sqrt{-g} \epsilon^{k l}\left(\partial_{k} \partial_{i} \zeta^{j}\right) \Gamma_{l j}^{i} \tag{5.12}
\end{align*}
$$

Similarly, the covariant anomaly is obtained in [43] as:

$$
\begin{align*}
\int d^{2} x \zeta_{i} \nabla_{j} \hat{T}^{i j}=2 \int P(\mathbf{M}, \mathbf{R}) & =-a \int\left(\nabla_{i} \zeta^{j}\right) R_{k l j}^{i} d x^{k} \wedge d x^{l} \\
= & -a \int \sqrt{-g}\left(\nabla_{i} z^{j}\right) \epsilon^{k l} R_{k l j}^{i} \tag{5.13}
\end{align*}
$$

where $\mathbf{M}=-\nabla_{i} \zeta^{j}$ is again a matrix-valued 0 -form and $R$ is the usual Ricci scalar. Finally, the improvement term $Y_{i j}$ is given as:

$$
\begin{equation*}
\int d^{2} x \sqrt{-g} Y^{i j} \delta g_{i j}=2 \int \operatorname{Tr}(\delta \boldsymbol{\Gamma} \wedge \mathbf{X}) \tag{5.14}
\end{equation*}
$$

in terms of the variation of the connection and a matrix-valued one-form $\mathbf{X}$ given again in terms of $P$. We refer to [43] for the exact expression for $\mathbf{X}$, which for $d=2$ however reduces immediately to $\mathbf{X}=a \boldsymbol{\Gamma}$. We therefore find:

$$
\begin{equation*}
\int d^{2} x \sqrt{-g} Y^{i j} \delta g_{i j}=2 a \int \sqrt{-g} \epsilon^{i j}\left(\delta \Gamma_{i k}^{l}\right) \Gamma_{j l}^{k} \tag{5.15}
\end{equation*}
$$

Let us now compare these results with our holographically computed expressions. Comparing (5.4) with (5.12) we find precise agreement provided that:

$$
\begin{equation*}
a=\frac{1}{16 G_{N}} \tag{5.16}
\end{equation*}
$$

Furthermore, we are now able to understand our original expression (5.1). Namely, it is exactly of the form:

$$
\begin{equation*}
\nabla^{i} T_{i j}=\nabla^{i} \hat{T}_{i j}-\nabla^{i} Y_{i j} . \tag{5.17}
\end{equation*}
$$

To see this, observe that the first term on the right-hand side of (5.1) agrees precisely with (5.13) and the second term is precisely $1 /\left(8 G_{N}\right) \nabla^{i} A_{i j}$ as can be seen by comparing (5.15) with (4.31). (This was recently noted in [45] as well.)

Notice that the energy-momentum tensor postulated in [40] does not include the term $\frac{1}{2} A_{i j}$ that we obtained in (4.37) from the variation of the on-shell supergravity action. The energy-momentum tensor of [40] is therefore precisely the tensor $\hat{T}_{i j}$ defined above. In agreement with the above discussion, this $\hat{T}_{i j}$ is not obtained from an on-shell action and the anomaly found there is precisely the covariant anomaly (5.13).

### 5.2 Weyl anomaly

For the Weyl anomaly we find from (4.38):

$$
\begin{equation*}
\left\langle T_{i}^{i}\right\rangle=\frac{1}{8 G_{N}}\left(R\left[g_{(0)}\right]+A_{i}^{i}\left[g_{(0)}\right]\right) \tag{5.18}
\end{equation*}
$$

We have already discussed that the extra term $A_{i}^{i}\left[g_{(0)}\right]$ can be removed by hand. We then obtain the trace of the covariant energy-momentum tensor:

$$
\begin{equation*}
\left\langle\hat{T}_{i}^{i}\right\rangle=\frac{1}{8 G_{N}} R\left[g_{(0)}\right] . \tag{5.19}
\end{equation*}
$$

On the other hand, in our conventions we should have:

$$
\begin{equation*}
\left\langle\hat{T}_{i}^{i}\right\rangle=\frac{c_{L}+c_{R}}{24} R\left[g_{(0)}\right] \tag{5.20}
\end{equation*}
$$

and therefore:

$$
\begin{equation*}
c_{L}+c_{R}=\frac{3}{G_{N}} \tag{5.21}
\end{equation*}
$$

which agrees with the analysis in section 6.4 .1 below.

## 6 Linearized analysis

In order to compute correlation functions involving the operator $t_{i j}$ as well, we will proceed perturbatively. In this section we therefore consider small perturbations $\delta G_{\mu \nu}=H_{\mu \nu}$ around the $\mathrm{AdS}_{3}$ background. We will first linearize the bulk equations of motion and solve these asymptotically in order to isolate the divergent pieces in the combined action $I_{\mathrm{C}}$ defined in (4.23). We then renormalize this action to second order in the fluctuations. Taking functional derivatives as in (4.36), we obtain finite expressions for the one-point functions of $T_{i j}$ and $t_{i j}$ in terms of the subleading coefficients in the radial expansion of the perturbations. Afterwards, we find the full linearized bulk solutions for $H_{i j}$ so we can express these subleading pieces as nonlocal functionals of the sources $g_{(0) i j}$ and $b_{(0) i j}$. Finally, a second functional derivative then gives all boundary two-point functions involving $T_{i j}$ and $t_{i j}$. At the end of this section we compare our results with those expected from a logarithmic CFT (LCFT) and find complete agreement.

### 6.1 Linearized equations of motion

We will now linearize the equations of section 4.1 around an empty AdS background solution. We work in Poincaré coordinates where the background metric $G_{\mu \nu}$ has the form

$$
\begin{equation*}
G_{\mu \nu} d x^{\mu} d x^{\nu}=\frac{d \rho^{2}}{4 \rho^{2}}+\frac{1}{\rho} \eta_{i j} d x^{i} d x^{j} . \tag{6.1}
\end{equation*}
$$

An earlier investigation of the linearized equations around this background can be found in $[4,8]$. As we work in Fefferman-Graham coordinates, it is natural to pick a radial-axial gauge for the fluctuations as well. Thus we set $H_{\rho \rho}=H_{\rho i}=0$ and define $h_{i j} \equiv \delta g_{i j}=$ $H_{i j} / \rho$. We therefore substitute

$$
\begin{equation*}
g_{i j}=\eta_{i j}+h_{i j} \tag{6.2}
\end{equation*}
$$

into the equations of motion (4.2). To leading order in $h_{i j}$ we find:

$$
\begin{align*}
&-\operatorname{tr}\left(h^{\prime \prime}\right)+\frac{1}{2 \mu} \epsilon^{i j} \partial_{i} \partial^{m} h_{m j}^{\prime}=0, \\
& 2 \rho \partial^{k} h_{i k}^{\prime \prime}+\partial^{k} h_{i k}^{\prime}+\mu \epsilon^{j k} \partial_{k} h_{i j}^{\prime}-\partial_{i} \operatorname{tr}\left(h^{\prime}\right)=0, \\
&-h_{i j}^{\prime \prime}+\eta_{i j} \frac{1}{2} \operatorname{tr}\left(h^{\prime \prime}\right)  \tag{6.3}\\
&+\frac{1}{\mu} \epsilon_{i}{ }^{k}\left[\frac{1}{4} \partial_{k} \partial^{l} h_{l j}^{\prime}+\frac{1}{4} \partial_{j} \partial^{l} h_{l k}^{\prime}-\frac{1}{2} \partial_{k} \partial_{j} \operatorname{tr}\left(h^{\prime}\right)+2 \rho h_{j k}^{\prime \prime \prime}+3 h_{j k}^{\prime \prime}\right]+(i \leftrightarrow j)=0,
\end{align*}
$$

and for the trace equation $R=-6$ we obtain:

$$
\begin{equation*}
-4 \rho \operatorname{tr}\left(h^{\prime \prime}\right)+\tilde{R}(h)+2 \operatorname{tr}\left(h^{\prime}\right)=0, \tag{6.4}
\end{equation*}
$$

with $\tilde{R}[h]$ the linearized curvature of $\eta_{i j}+h_{i j}$, which can be explicitly written as

$$
\begin{equation*}
\tilde{R}[h]=\nabla^{i} \nabla^{j} h_{i j}-\nabla^{i} \nabla_{i} \operatorname{tr}(h) . \tag{6.5}
\end{equation*}
$$

Notice that all covariant symbols and traces in the above equations are defined using the background metric $\eta_{i j}$.

We also obtained the linearized equations of motion in global coordinates, which can be found in appendix C. The analysis in global coordinates would be useful should one want to compute directly ${ }^{5}$ the correlators of the CFT on $R \times S^{1}$ rather than $R^{2}$.

### 6.2 Holographic renormalization

In this subsection we consider the holographic renormalization of the on-shell action. Since we work at the linearized level, we compute the on-shell action to second order in the perturbations around the Poincaré background. We isolate the divergences to that order and compute the necessary covariant counterterms to cancel these divergences.

[^4]
### 6.2.1 Asymptotic analysis

We begin by substituting the asymptotic expansion for $h_{i j}$ :

$$
\begin{equation*}
h_{i j}=b_{(0) i j} \log (\rho)+h_{(0) i j}+b_{(2) i j} \rho \log (\rho)+h_{(2) i j} \rho+\ldots \tag{6.6}
\end{equation*}
$$

into the linearized equations of motion (6.3) and (6.4). We find from the linearization of the asymptotic analysis above that:

$$
\begin{align*}
\operatorname{tr}\left(b_{(0)}\right) & =0, \\
b_{i j}+\epsilon_{i}^{k} b_{k j} & =0, \\
\operatorname{tr}\left(b_{(2)}\right) & =-\frac{1}{2} \tilde{R}\left[b_{(0)}\right]=-\frac{1}{2} \partial^{i} \partial^{j} b_{(0) i j}, \\
\operatorname{tr}\left(h_{(2)}\right) & =-\frac{1}{2} \tilde{R}\left[h_{(0)}\right]+\operatorname{tr}\left(b_{(2)}\right),  \tag{6.7}\\
b_{(2) i j}-\epsilon_{i}^{k} b_{(2) k j} & =\frac{1}{2} \eta_{i j} \operatorname{tr}\left(b_{(2)}\right)+\frac{1}{4} \epsilon_{i}^{k}\left(\partial_{k} \partial^{l} b_{(0) l j}+\partial_{j} \partial^{l} b_{(0) l k}\right), \\
\partial^{j}\left(b_{(2) i j}-3 \epsilon_{i}^{k} b_{(2) k j}\right. & \left.+2 \bar{P}_{i}^{k} h_{(2) k j}-2 \bar{P}_{i}^{k} \eta_{k j}\left(\operatorname{tr}\left(h_{(2)}\right)+\operatorname{tr}\left(b_{(2)}\right)\right)\right)=0,
\end{align*}
$$

where all covariant symbols and traces are defined using $\eta_{i j}$ and $\tilde{R}[h]$ again denotes the linearized curvature of the metric $\eta_{i j}+h_{i j}$.

### 6.2.2 On-shell action and counterterms

The next step is to substitute the asymptotic expansion (6.6), together with the constraints (6.7), into the on-shell action (4.23). We then isolate the divergences and find the necessary counterterm action that makes the action finite to second order $h_{i j}$.

Expanding the on-shell action (4.23) in $h_{i j}$, we find that the first-order term vanishes, since it gives a term proportional to the bulk equations of motion plus the surface terms of (4.30), which vanish identically for the Poincaré background. At the second order we find:

$$
\begin{equation*}
I_{2}=\frac{1}{32 \pi G_{N}} \int d^{2} x\left(h_{i j}^{\prime}-\eta_{i j} \operatorname{tr}\left(h^{\prime}\right)-2 \rho \epsilon_{i}^{k} h_{k j}^{\prime \prime}-\epsilon_{i}{ }^{k} h_{k j}^{\prime}\right) h^{i j} \tag{6.8}
\end{equation*}
$$

Notice that there are no contributions from the $A_{i j}$-term for the Poincaré background, as can be seen easily from its definition (4.31). If we now substitute the expansion (6.6) and use the linearized equations of motion (6.7) then we find a logarithmic divergence of the form:

$$
\begin{equation*}
I_{2}=\frac{1}{32 \pi G_{N}} \int d^{2} x\left(\frac{1}{2} \operatorname{tr}\left(h_{(0)}\right) \tilde{R}\left[b_{(0)}\right]-2 b_{(2) i j} b_{(0)}^{i j}-\frac{1}{2} h_{(0) i}^{k} \partial^{i} \partial^{j} b_{(0) j k}\right) \log (\rho)+\ldots \tag{6.9}
\end{equation*}
$$

The next step in the holographic renormalization is to invert the series and rewrite the divergent terms in terms of $h_{i j}$ plus finite corrections. This gives:

$$
\begin{align*}
\log (\rho) b_{(0) i j} & =h_{i j}+\ldots, \\
h_{(0) i j} & =h_{i j}-\rho \log (\rho) h_{i j}^{\prime}+\ldots,  \tag{6.10}\\
\log (\rho) b_{(2) i j} b_{(0)}^{i j} & =\frac{1}{2} \rho h_{i j}^{\prime} h^{\prime i j}+\ldots,
\end{align*}
$$

and we also have:

$$
\begin{equation*}
\operatorname{tr}\left(h_{(0)} \tilde{R}\left[b_{(0)}\right]=2 h_{(0) i}^{k} \partial^{i} \partial^{j} b_{(0) j k}-h^{i j} \partial^{k} \partial_{k} b_{(0) i j},\right. \tag{6.11}
\end{equation*}
$$

from which we find that this divergence is cancelled by adding the following counterterm action:

$$
\begin{equation*}
I_{2, \mathrm{ct}}=\frac{1}{32 \pi G_{N}} \int d^{2} x\left(\frac{1}{4} h^{i j} \partial^{k} \partial_{k} h_{i j}+\rho h_{i j}^{\prime} h^{i j}-\frac{1}{4} h_{i}^{j} \partial^{i} \partial^{k} h_{k j}\right) . \tag{6.12}
\end{equation*}
$$

This action can be written in a covariant form as follows. The background induced metric is written $\gamma_{i j}=\eta_{i j} / \rho$ and its deviation $h_{i j} / \rho=\sigma_{i j}$. The extrinsic curvature $K_{i}^{j}=-\delta_{i}^{j}+\rho g_{i}^{\prime j}$ and its deviation is $\tilde{K}_{i}^{j}[h]=\rho h_{i}^{\prime j}$. In this notation, the counterterm action becomes:

$$
\begin{equation*}
I_{2, \mathrm{ct}}=\frac{1}{32 \pi G_{N}} \int d^{2} x \sqrt{-\gamma}\left(\frac{1}{4} \sigma^{i j} \nabla^{k} \nabla_{k} \sigma_{i j}+\tilde{K}_{i j}[h] \tilde{K}^{i j}[h]-\frac{1}{4} \sigma_{i}^{j} \nabla^{i} \nabla^{k} \sigma_{k j}\right), \tag{6.13}
\end{equation*}
$$

where indices are now raised and covariant derivatives and traces are defined using $\gamma_{i j}$.
Notice that the counterterm action involves the extrinsic curvature $K_{i j}$ as well. Such a term would not be allowed in pure Einstein theory as it would lead to an incorrect variational principle. On the other hand, for TMG we already found that the variational principle is different. In particular, the higher-derivative terms allow for the specification of both $\gamma_{i j}$ and $K_{i j}$ at the boundary and therefore we are also allowed to use $K_{i j}$ in the boundary counterterm action.

### 6.2.3 One-point functions

For the total action at this order $I_{2, \text { tot }}=I_{2}+I_{2, \text { ct }}$ we find the variations:

$$
\begin{align*}
& \frac{\delta I_{2, \text { tot }}}{\delta h^{i j}}=\frac{1}{16 \pi G_{N}}\left(h_{i j}^{\prime}-\eta_{i j} \operatorname{tr}\left(h^{\prime}\right)-2 \rho \epsilon_{i}^{k} h_{k j}^{\prime \prime}-\epsilon_{i}^{k} h_{k j}^{\prime}+\frac{1}{2} \tilde{A}_{i j}[h]+\frac{1}{4} \partial^{k} \partial_{k} h_{i j}-\frac{1}{4} \partial_{i} \partial^{k} h_{k j}\right), \\
& \frac{\delta I_{2, \text { tot }}}{\delta h^{i j}}=\frac{1}{16 \pi G_{N}} \rho\left(\delta_{i}^{k}+\epsilon_{i}^{k}\right) h_{k j}^{\prime}, \tag{6.14}
\end{align*}
$$

with $\tilde{A}_{i j}[h]$ the linearization of $A_{i j}$ as defined in (4.31):

$$
\begin{equation*}
\tilde{A}_{i j}[h]=\frac{1}{4} \epsilon_{i}^{k}\left(\partial_{j} \partial^{l} h_{k l}-\partial^{l} \partial_{l} h_{k j}\right)+(i \leftrightarrow j) . \tag{6.15}
\end{equation*}
$$

We now substitute the expansion (6.6) and find:

$$
\begin{align*}
& \frac{\delta I_{2, \text { tot }}}{\delta h^{i j}}=\frac{1}{16 \pi G_{N}}\left\{b_{(2) i j}-3 \epsilon_{i}{ }^{k} b_{(2) k j}+2 \bar{P}_{i}^{k} h_{(2) k j}+\eta_{i j}\left(\frac{1}{2} \tilde{R}\left[h_{(0)}\right]+\tilde{R}\left[b_{(0)}\right]\right)\right. \\
& \left.+\frac{1}{2} \bar{P}_{i}^{k}\left(\partial^{l} \partial_{l} h_{(0) k j}-\partial_{j} \partial^{l} h_{(0) l k}\right)\right\},  \tag{6.16}\\
& \frac{\delta I_{2, \text { tot }}}{\delta h^{i j}}=\frac{\rho}{8 \pi G_{N}} P_{i}^{k}\left(b_{(2) k j} \log (\rho)+b_{(2) k j}+h_{(2) k j}\right),
\end{align*}
$$

where we dropped terms that vanish as $\rho \rightarrow 0$ and do not contribute below. In the above formulas symmetrization in $i$ and $j$ is implicit. When $b_{(0) i j}=0$ we can compare the first
of these expressions with (4.37) and we find that the additional counterterms only change the local terms.

Using (4.36) and taking into account an extra sign from the fact that $g^{i j}=\eta^{i j}-h^{i j}$, we obtain the following explicit expression for the one-point functions:

$$
\begin{align*}
\left\langle T_{i j}\right\rangle= & \lim _{\rho \rightarrow 0} \frac{4 \pi}{\sqrt{-\eta}} \frac{\delta I_{2, \text { tot }}}{\delta h^{i j}} \\
= & \frac{1}{4 G_{N}}\left\{b_{(2) i j}-3 \epsilon_{i}^{k} b_{(2) k j}+2 \bar{P}_{i}^{k} h_{(2) k j}+\eta_{i j}\left(\frac{1}{2} \tilde{R}\left[h_{(0)}\right]+\tilde{R}\left[b_{(0)}\right]\right)\right. \\
& \left.+\frac{1}{2} \bar{P}_{i}^{k}\left(\partial^{l} \partial_{l} h_{(0) k j}-\partial_{j} \partial^{l} h_{(0) l k}\right)\right\},  \tag{6.17}\\
\left\langle t_{i j}\right\rangle= & \lim _{\rho \rightarrow 0}\left(\frac{-4 \pi}{\rho \sqrt{-g}} \frac{\delta I}{\delta h^{i j}}-\log (\rho) \frac{4 \pi}{\sqrt{-\eta}} \frac{\delta I}{\delta h^{i j}}\right)_{L}=\frac{1}{2 G_{N}}\left(b_{(2) i j}+h_{(2) i j}\right)_{L},
\end{align*}
$$

where we note that the projection to the $L$-component in $\left\langle t_{i j}\right\rangle$ also removes (divergent) terms of the form $\eta_{i j}(\ldots)$ or $\bar{P}_{i}^{k}(\ldots)_{k j}$.

### 6.3 Exact solutions

In this subsection we solve the linearized equations of motion given in section 6.2.1. From the explicit solutions we find below, we can obtain the subleading terms $b_{(2) i j}$ and $h_{(2) i j}$ that enter in (6.17) as nonlocal functionals of $g_{(0) i j}$ and $b_{(0) i j}$. This will allow us to carry out the second functional differentiation required to obtain the two-point functions.

In explicitly solving the fluctuation equations it is convenient to Wick rotate and work in Euclidean signature; the procedure for analytic continuation is explained in detail in appendix B. Concretely, one starts from the metric (6.1), introduces lightcone coordinates $u=t+x, v=-t+x$, and replaces $v \rightarrow z, u \rightarrow \bar{z}$ with $(z, \bar{z})$ complex boundary coordinates. The background metric then has the form:

$$
\begin{equation*}
d s^{2}=\frac{d \rho^{2}}{4 \rho^{2}}+\frac{1}{\rho} d z d \bar{z} . \tag{6.18}
\end{equation*}
$$

We will employ the notation $\partial \equiv \partial_{z}$ and $\bar{\partial} \equiv \partial_{\bar{z}}$ below.
In these coordinates, the linearized equations of motion (6.3) and (6.4) become:

$$
\begin{align*}
-\bar{\partial}(1+\mu) h_{z \bar{z}}^{\prime}+\partial(1+\mu) h_{\bar{z} \bar{z}}^{\prime}+2 \rho\left(\partial h_{\bar{z} \bar{z}}^{\prime \prime}+\bar{\partial} h_{z \bar{z}}^{\prime \prime}\right) & =0 \\
\partial(1-\mu) h_{z \bar{z}}^{\prime}-\bar{\partial}(1-\mu) h_{z z}^{\prime}-2 \rho\left(\partial h_{z \bar{z}}^{\prime \prime}+\bar{\partial} h_{z z}^{\prime \prime}\right) & =0 \\
-\bar{\partial}^{2} h_{z \bar{z}}^{\prime}+\bar{\partial} \partial h_{\bar{z} \bar{z}}^{\prime}+(3+\mu) h_{\bar{z} \bar{z}}^{\prime \prime}+2 \rho h_{\bar{z} \bar{z}}^{(3)} & =0  \tag{6.19}\\
-\partial^{2} h_{z \bar{z}}^{\prime}+\bar{\partial} \partial h_{z z}^{\prime}+(3-\mu) h_{z z}^{\prime \prime}+2 \rho h_{z z}^{(3)} & =0 \\
\partial^{2} h_{\bar{z} \bar{z}}^{\prime}-\bar{\partial}^{2} h_{z z}^{\prime}+2 \mu h_{z \bar{z}}^{\prime \prime} & =0 \\
\partial^{2} h_{\bar{z} \bar{z}}-2 \bar{\partial} \partial h_{z \bar{z}}+\bar{\partial}^{2} h_{z z}+2 h_{z \bar{z}}^{\prime}-4 \rho h_{z \bar{z}}^{\prime \prime} & =0,
\end{align*}
$$

where again we have temporarily reinstated $\mu$ for later use. From these equations it is straightforward to verify that $h_{z \overline{\mathcal{Z}}}^{\prime \prime}$ satisfies a Bessel-like equation:

$$
\begin{equation*}
4 \rho^{2} h_{z \bar{z}}^{(4)}+8 \rho h_{z \bar{z}}^{(3)}+\left(4 \rho \bar{\partial} \partial-\mu^{2}+1\right) h_{z \bar{z}}^{\prime \prime}=0, \tag{6.20}
\end{equation*}
$$

which has the general solution:

$$
\begin{equation*}
h_{z \bar{z}}^{\prime \prime}=\rho^{-1 / 2} K_{\mu}(q \sqrt{\rho}) \alpha+\rho^{-1 / 2} I_{\mu}(q \sqrt{\rho}) \beta, \tag{6.21}
\end{equation*}
$$

with $\alpha$ and $\beta$ arbitrary functions of $u$ and $v$ and we defined $q=\sqrt{-4 \bar{\partial} \partial}$. Passing to momentum space, we have $q \geq 0$ and only $K_{\mu}$ is regular as $\rho \rightarrow \infty$ and we therefore set $\beta=0$.

As a sidenote, in real time it is possible that $q<0$ and then both solutions have a power-law divergence as $\rho \rightarrow \infty$. A solution that is regular at $\rho \rightarrow \infty$ can nevertheless be constructed from them using an infinite number of these modes [4, 8]; see also [31] for an explicit example. Alternatively, one can solve the fluctuation equation using global coordinates. In any case, since we work in Euclidean signature such singular behavior for the individual modes is absent and there is no need to worry about these issues.

We can integrate (6.21) twice to find an explicit solution for $h_{z \bar{z}}$ which for general $\mu$ involves an integral of the hypergeometric functions ${ }_{1} F_{2}$. Notice also that as $\mu \rightarrow \infty$ the linearized Einstein equations become $h_{z \bar{z}}^{\prime \prime}=0$, so the radial dependence of the perturbation is linear in $\rho$. This correctly reproduces the linearization of the exact solution of the non-linear vacuum Einstein equation in three dimension in Fefferman-Graham coordinates given in [47], which has a Fefferman-Graham expansion that terminates at $\rho^{2}$.

For the other components, the last two equations in (6.19) may be exploited to find that:

$$
\begin{align*}
& 2 \partial^{2} h_{\bar{z} \bar{z}}^{\prime}=4 \rho h_{z \bar{z}}^{(3)}+2(1-\mu) h_{z \bar{z}}^{\prime \prime}+2 \bar{\partial} \partial h_{z \bar{z}}^{\prime}, \\
& 2 \bar{\partial}^{2} h_{z z}^{\prime}=4 \rho h_{z \bar{z}}^{(3)}+2(1+\mu) h_{z \bar{z}}^{\prime \prime}+2 \bar{\partial} \partial h_{z \bar{z}}^{\prime}, \tag{6.22}
\end{align*}
$$

which allows us to completely solve the system.

### 6.3.1 Solutions for $\mu=1$

In contrast to the case for general $\mu$, for $\mu=1$ one may use the modified Bessel equation:

$$
\begin{equation*}
\partial_{x}^{2}\left(\sqrt{x} K_{1}(\sqrt{x})\right)=\frac{1}{4 \sqrt{x}} K_{1}(\sqrt{x}) \tag{6.23}
\end{equation*}
$$

to integrate (6.21) twice giving:

$$
\begin{equation*}
h_{z \bar{z}}=B_{z \bar{z}} \partial^{2} c_{0}+c_{1} \rho+c_{2}, \tag{6.24}
\end{equation*}
$$

where $c_{i}$ are integration constants which are arbitrary functions of $\bar{z}$ and $z$ and we defined

$$
\begin{equation*}
B_{z \bar{z}} \equiv-\frac{2 \sqrt{\rho}}{q} K_{1}(q \sqrt{\rho}) . \tag{6.25}
\end{equation*}
$$

Notice that it is convenient to express $h_{z \bar{z}}^{\prime \prime}$ as:

$$
\begin{equation*}
h_{z \bar{z}}^{\prime \prime}=-\frac{1}{\rho} B_{z \bar{z}} \bar{\partial} \partial^{3} c_{0} . \tag{6.26}
\end{equation*}
$$

Integrating (6.22) then results in:

$$
\begin{align*}
& h_{\bar{z} \bar{z}}=-B_{z \bar{z}} \partial \bar{\partial} c_{0}-2 B_{z \bar{z}}^{\prime} c_{0}+\frac{\bar{\partial}}{\partial} c_{1} \rho+c_{3}, \\
& h_{z z}=-B_{z \bar{z}} \frac{\partial^{3}}{\bar{\partial}} c_{0}+\frac{\partial}{\bar{\partial}} c_{1} \rho+c_{4}, \tag{6.27}
\end{align*}
$$

and the last equation in (6.19) gives the constraint:

$$
\begin{equation*}
2 c_{1}+\bar{\partial}^{2} c_{4}+\partial^{2} c_{3}-2 \bar{\partial} \partial c_{2}=0, \tag{6.28}
\end{equation*}
$$

i.e. $c_{1}$ is not an independent integration constant, but is determined in terms of the other integration constants.

Near the boundary $\rho \rightarrow 0$ we have the following expansion:

$$
\begin{equation*}
B_{z \bar{z}}=-\frac{2}{q^{2}}-\frac{\rho}{2}(2 \gamma-1)-\rho \log \left(\frac{q \sqrt{\rho}}{2}\right)-\frac{q^{2} \rho^{2}}{8} \log \left(\frac{q \sqrt{\rho}}{2}\right)+\ldots, \tag{6.29}
\end{equation*}
$$

with $\gamma$ the Euler-Mascheroni constant. Substitution in (6.27) then yields the expansions for the components:

$$
\begin{align*}
& h_{z \bar{z}}=h_{(0) z \bar{z}}-\frac{1}{2} \rho \log (\rho) \partial^{2} b_{(0) \bar{z} \bar{z}}+\rho h_{(2) z \bar{z}}+\ldots,  \tag{6.30}\\
& h_{\bar{z} \bar{z}}=b_{(0) \bar{z} \bar{z}} \log (\rho)+h_{(0) \bar{z} \bar{z}}-\frac{1}{2} \rho \log (\rho) \bar{\partial} \partial b_{(0) \bar{z} \bar{z}}+\rho\left[\frac{\bar{\partial}}{\partial} h_{(2) z \bar{z}}+\frac{4 \gamma-3}{2} \bar{\partial} \partial b_{(0) \bar{z} \bar{z}}\right]+\ldots, \\
& h_{z z}=h_{(0) z z}+\frac{1}{2} \rho \log (\rho) \frac{\partial^{3}}{\bar{\partial}} b_{(0) \bar{z} \bar{z}}+\rho\left[\left(2 \gamma-1+2 \log \left(\frac{q}{2}\right)\right) \frac{\partial^{3}}{\bar{\partial}} b_{(0) \bar{z} \bar{z}}+\frac{\partial}{\bar{\partial}} h_{(2) z \bar{z}}\right]+\ldots,
\end{align*}
$$

where the boundary sources $h_{(0) i j}$ and $b_{(0) \bar{z} \bar{z}}$ are given by the following combinations of the integration constants $c_{i}$ :

$$
\begin{array}{ll}
h_{(0) z \bar{z}}=c_{2}-\frac{2}{q^{2}} \partial^{2} c_{0} & h_{(0) z z}=c_{4}-\frac{1}{2} \frac{\partial^{2}}{\bar{\partial}^{2}} c_{0} \\
h_{(0) \bar{z} \bar{z}}=c_{3}-\frac{1}{2} c_{0}+2 \gamma c_{0}+2 \log \left(\frac{q}{2}\right) c_{0} & b_{(0) \bar{z} \bar{z}}=c_{0} . \tag{6.31}
\end{array}
$$

The normalizable mode is the combination:

$$
\begin{equation*}
h_{(2) z \bar{z}}=c_{1}-\frac{2 \gamma-1}{2} \partial^{2} c_{0}-\log \left(\frac{q}{2}\right) \partial^{2} c_{0}, \tag{6.32}
\end{equation*}
$$

which using (6.28) is determined by the boundary sources via:

$$
\begin{equation*}
h_{(2) z \bar{z}}=-\frac{1}{2} \partial^{2} h_{(0) \bar{z} \bar{z}}-\frac{1}{2} \bar{\partial}^{2} h_{(0) z z}+\bar{\partial} \partial h_{(0) z \bar{z}}-\frac{1}{2} \partial^{2} b_{(0) \bar{z} \bar{z}} . \tag{6.33}
\end{equation*}
$$

This is indeed the linearized form of (4.13) and (4.10) combined. Notice also that the radial expansion (6.30) indeed shows the same asymptotic behavior as (4.4) in section 4.2.

### 6.4 Two-point functions

Substituting the solutions that we found above into the holographic one point functions (6.17), we find that:

$$
\begin{align*}
& \left\langle t_{z z}\right\rangle=\frac{-1}{4 G_{N}}\left((4 \gamma-1) \frac{\partial^{3}}{\bar{\partial}} b_{(0)} \bar{z} \bar{z}+4 \log \left(\frac{q}{2}\right) \frac{\partial^{3}}{\bar{\partial}} b_{(0) \bar{z} \bar{z}}+2 \frac{\partial}{\bar{\partial}} h_{(2) z \bar{z}}\right), \\
& \left\langle T_{z \bar{z}}\right\rangle=\text { local }, \\
& \left\langle T_{z z}\right\rangle=-\frac{1}{4 G_{N}}\left(\frac{\partial^{3}}{\bar{\partial}} b_{(0) z z}+\text { local }\right),  \tag{6.34}\\
& \left\langle T_{\bar{z} \bar{z}}\right\rangle=\frac{1}{2 G_{N}}\left(\frac{\bar{\partial}}{\partial} h_{(2) z \bar{z}}+\text { local }\right),
\end{align*}
$$

where the local pieces correspond to finite contact terms.
We now turn to the position space expressions for the two-point functions. These are obtained via the following functional differentiations:

$$
\begin{equation*}
\left\langle T_{i j} \ldots\right\rangle=i \frac{4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta}{\delta g_{(0)}^{i j}}\langle\ldots\rangle, \quad\left\langle t_{i j} \ldots\right\rangle=i \frac{4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta}{\delta b_{(0)}^{i j}}\langle\ldots\rangle, \tag{6.35}
\end{equation*}
$$

where the prefactors are explained in appendix B. Notice that in complex coordinates $d s^{2}=d z d \bar{z}$ so $\sqrt{-g_{(0)}}=1 / 2$ whilst in our case $g^{i j}=\eta^{i j}-h^{i j}$ and therefore

$$
\begin{equation*}
\frac{\delta}{\delta g^{i j}}=-\frac{\delta}{\delta h^{i j}}=-\eta_{i k} \eta_{j l} \frac{\delta}{\delta h_{k l}} \tag{6.36}
\end{equation*}
$$

which in complex coordinates becomes:

$$
\begin{equation*}
\frac{\delta}{\delta g_{(0)}^{z z}}=-\frac{1}{4} \frac{\delta}{\delta h_{\bar{z} \bar{z}}}, \quad \quad \frac{\delta}{\delta g_{(0)}^{\bar{z} \bar{z}}}=-\frac{1}{4} \frac{\delta}{\delta h_{z z}} \tag{6.37}
\end{equation*}
$$

Functionally differentiating the one point functions thus results in:

$$
\begin{align*}
\left\langle t_{z z}(z, \bar{z}) t_{z z}(0)\right\rangle & =-\frac{2 \pi i}{G_{N}}\left[\left(\gamma-\frac{1}{4}\right)+\log \left(\frac{q}{2}\right)\right] \frac{\partial^{3}}{\bar{\partial}} \delta^{2}(z, \bar{z}) \\
\left\langle t_{z z}(z, \bar{z}) T_{z z}(0)\right\rangle & =-\frac{i \pi}{2 G_{N}} \frac{\partial^{3}}{\bar{\partial}} \delta^{2}(z, \bar{z})  \tag{6.38}\\
\left\langle T_{\bar{z} \bar{z}}(z, \bar{z}) T_{\bar{z} \bar{z}}(0)\right\rangle & =\frac{i \pi}{2 G_{N}} \frac{\bar{\partial}^{3}}{\partial} \delta^{2}(z, \bar{z})
\end{align*}
$$

whilst $\left\langle t_{z z} T_{\bar{z} \bar{z}}\right\rangle=\left\langle T_{\bar{z} \bar{z}} T_{z z}\right\rangle=\left\langle T_{z z} T_{z z}\right\rangle=0$ up to contact terms.
These expressions can be evaluated using the following set of identities. First notice that:

$$
\begin{equation*}
-2 i \delta^{2}(z, \bar{z})=\delta(x) \delta(\tau), \quad 4 \partial \bar{\partial}=\partial_{\tau}^{2}+\partial_{x}^{2} \tag{6.39}
\end{equation*}
$$

The former of these is obtained by requesting $\int d^{2} z \delta^{2}(z, \bar{z})=1$ and $\frac{1}{2} \int d^{2} z(\ldots)=$ $-i \int d^{2} x(\ldots)$. We also need the following integral, which can be directly computed using the properties of the Bessel function $J_{0}(x)$ :

$$
\begin{equation*}
\frac{1}{4 \pi^{2}} \int d \omega d k e^{i \omega \tau+i k x} \frac{1}{\left(\omega^{2}+k^{2}\right)^{\alpha / 2}}=\frac{1}{\pi} 2^{-\alpha} \frac{\Gamma(1-\alpha / 2)}{\Gamma(\alpha / 2)}\left(\tau^{2}+x^{2}\right)^{-1+(\alpha / 2)} \tag{6.40}
\end{equation*}
$$

Taking the limit $\alpha=2$ on both sides gives the identity:

$$
\begin{equation*}
\frac{1}{\partial \bar{\partial}} \delta^{2}(z, \bar{z})=\frac{2 i}{\partial_{\tau}^{2}+\partial_{x}^{2}} \delta^{2}(x, y)=\frac{i}{2 \pi} \log \left(m^{2}\left(\tau^{2}+x^{2}\right)\right)=\frac{i}{2 \pi} \log \left(m^{2}|z|^{2}\right) \tag{6.41}
\end{equation*}
$$

where $m$ is a scale. By differentiating both sides in (6.40) with respect to $\alpha$ we also find:

$$
\begin{equation*}
\log (q) \frac{1}{\partial \bar{\partial}} \delta^{2}(z, \bar{z})=\log (q) \frac{2 i}{\partial_{\tau}^{2}+\partial_{x}^{2}} \delta^{2}(x, y)=-\frac{i}{8 \pi} \log ^{2}\left(m^{2}\left(\tau^{2}+x^{2}\right)\right)=-\frac{i}{8 \pi} \log ^{2}\left(m^{2}|z|^{2}\right) \tag{6.42}
\end{equation*}
$$

Using these expressions the two-point functions become:

$$
\begin{align*}
\left\langle t_{z z}(z, \bar{z}) t_{z z}(0)\right\rangle & =\frac{1}{4 G_{N}} \partial^{4}\left[B_{m} \log \left(m^{2}|z|^{2}\right)-\log ^{2}\left(m^{2}|z|^{2}\right)\right] \\
& =\frac{1}{2 G_{N}} \frac{-3 B_{m}-11+6 \log \left(m^{2}|z|^{2}\right)}{z^{4}}  \tag{6.43}\\
\left\langle t_{z z}(z, \bar{z}) T_{z z}(0)\right\rangle & =\frac{1}{4 G_{N}} \partial^{4} \log \left(m^{2}|z|^{2}\right)=\frac{-3 /\left(2 G_{N}\right)}{z^{4}} \\
\left\langle T_{\bar{z} \bar{z}}(z, \bar{z}) T_{\bar{z} \bar{z}}(0)\right\rangle & =\frac{3 /\left(2 G_{N}\right)}{\bar{z}^{4}}
\end{align*}
$$

where $B_{m}$ is a scale-dependent constant that can be changed by rescaling $m$ in the first line. In fact, the entire non-logarithmic piece in the second line can also be removed from the correlation function by redefining $t \rightarrow t-\left(3 B_{m}+11\right) T_{z z} / 6$. This transformation is familiar from logarithmic CFT as we review in appendix $D$.

### 6.4.1 Comparison to logarithmic CFT

The expressions above agree with general expectations from a logarithmic CFT, see appendix D for an introduction. The central charges can be computed as follows. From the two-point functions of $T_{\bar{z} \bar{z}}$ and $T_{z z}$, which should be of the form:

$$
\begin{equation*}
\left\langle T_{z z} T_{z z}\right\rangle=\frac{c_{L}}{2 z^{4}}, \quad\left\langle T_{\bar{z} \bar{z}} T_{\bar{z} \bar{z}}\right\rangle=\frac{c_{R}}{2 \bar{z}^{4}} \tag{6.44}
\end{equation*}
$$

we find that

$$
\begin{equation*}
c_{L}=0, \quad c_{R}=\frac{3}{G_{N}} \tag{6.45}
\end{equation*}
$$

which agrees with [3]. As discussed in appendix D two point functions of a logarithmic pair of operators $(T, t)$ in a LCFT have the structure:

$$
\begin{array}{rlr}
\langle T(z) T(0)\rangle & =0 ; & \langle T(z) t(0,0)\rangle=\frac{b}{2 z^{4}}  \tag{6.46}\\
\langle t(z, \bar{z}) t(0,0)\rangle & =\frac{-b \log \left(m^{2}|z|^{2}\right)}{z^{4}}
\end{array}
$$

Note that by rescaling the operator $t$ the coefficients of the non-zero two point functions can be changed; there is however a distinguished normalization of the operator in which the two point functions take this form, and the coefficient $b$ is sometimes referred to as the new anomaly, see [48]. Comparing these expressions with (6.43) we see that our holographic
two point functions indeed have the structure expected from a LCFT and the coefficient $b$ is:

$$
\begin{equation*}
b=-\frac{3}{G_{N}} . \tag{6.47}
\end{equation*}
$$

This value will be confirmed below in the analysis for general $\mu$.

## 7 Linearized analysis for general $\mu$

In this section we repeat the linearized analysis of section 6 for general $\mu$ around the Poincaré background. We define:

$$
\begin{equation*}
\lambda=\frac{1}{2}(\mu-1), \quad \mu=2 \lambda+1, \tag{7.1}
\end{equation*}
$$

and we work around $\lambda=0$.

### 7.1 Asymptotic analysis

The linearized equations of motion give the most general asymptotic form of the solution:

$$
\begin{equation*}
h_{i j}=h_{(-2 \lambda) i j} \rho^{-\lambda}+h_{(0) i j}+h_{(2) i j} \rho+h_{(2-2 \lambda) i j} \rho^{1-\lambda}+h_{(2+2 \lambda) i j} \rho^{\lambda+1}+\ldots, \tag{7.2}
\end{equation*}
$$

with the conditions:

$$
\begin{array}{ccc}
\operatorname{tr}\left(h_{(-2 \lambda)}\right)=0 & P_{i}^{k} h_{(-2 \lambda) k j}=0 & \operatorname{tr}\left(h_{(2)}\right)=-\frac{1}{2} \tilde{R}\left[h_{(0)}\right] \\
\operatorname{tr}\left(h_{(2-2 \lambda)}\right)=\frac{-\tilde{R}\left[h_{(-2 \lambda)}\right]}{2(1-\lambda)(2 \lambda+1)} & \operatorname{tr}\left(h_{(2 \lambda+2)}\right)=0 & \bar{P}_{i}^{k} h_{(2 \lambda+2) k j}=0  \tag{7.3}\\
h_{(2-2 \lambda) i j}+\frac{2 \lambda-1}{2 \lambda+1} \epsilon_{i}^{k} h_{(2-2 \lambda) k j}=\frac{1}{2} \eta_{i j} \operatorname{tr}\left(h_{(2-2 \lambda)}\right)+\frac{\epsilon_{i}^{k}\left(\partial_{k} \partial^{l} h_{(-2 \lambda) l j}+\partial_{j} \partial^{l} h_{(-2 \lambda) l k}\right)}{4(1-\lambda)(2 \lambda+1)} .
\end{array}
$$

Notice that for integer values of $\mu$ we see from the explicit solutions below that a logarithmic mode appears. In what follows we will consider only the case $0<|\mu|<2$ so $|\lambda|<\frac{1}{2}$, with $|\mu|=1$ the special point discussed above, so such logarithmic modes are not required. It would be straightforward to generalize the linearized analysis to other values of $\lambda$, whilst for $\lambda<0$ the corresponding dual operator is relevant and thus there is no obstruction to carrying out a full non-linear analysis of the system.

Substituting the expansions into the on-shell action, the second term in the expansion of the on-shell action $I_{2}$ was defined for $\mu=1$ in (6.8) and now becomes:

$$
\begin{equation*}
I_{2, \lambda}=\frac{1}{32 \pi G_{N}} \int d^{2} x\left(h_{i j}^{\prime}-\eta_{i j} \operatorname{tr}\left(h^{\prime}\right)-2 \rho \frac{1}{2 \lambda+1} \epsilon_{i}^{k} h_{k j}^{\prime \prime}-\frac{1}{(2 \lambda+1)} \epsilon_{i}^{k} h_{k j}^{\prime}\right) h^{i j} . \tag{7.4}
\end{equation*}
$$

Substituting (7.2), we find that this action is again divergent if $h_{(-2 \lambda)}$ is nonzero and if $\lambda>0$, with a leading piece of the form:

$$
\begin{equation*}
I_{2, \lambda}=\frac{1}{32 \pi G_{N} \mu} \int d^{2} x\left(\frac{1}{2} \operatorname{tr}\left(h_{(0)}\right) \tilde{R}\left[h_{(-2 \lambda)}\right]-2 \lambda h_{(2) i j} h_{(-2 \lambda)}^{i j}-\frac{1}{2} h_{(0) i}^{k} \partial^{i} \partial^{j} h_{(-2 \lambda) j k}\right) \rho^{-\lambda}+\ldots \tag{7.5}
\end{equation*}
$$

This term is cancelled precisely by adding $I_{2, \mathrm{ct}} /(2 \lambda+1)$, where $I_{2, \mathrm{ct}}$ is the counterterm action for $\mu=1$ defined in (6.12). For $\lambda<0$ there is no divergence but the counterterm action is then finite as well and we will continue to include it.

The variation of the total action $I_{2, \lambda, \text { tot }}=I_{2, \lambda}+I_{2, \text { ct }} /(2 \lambda+1)$ is similar to (6.14):

$$
\begin{align*}
\frac{\delta I_{2, \lambda, \text { tot }}}{\delta h^{i j}}= & \frac{1}{16 \pi G_{N}}\left(h_{i j}^{\prime}-\eta_{i j} \operatorname{tr}\left(h^{\prime}\right)\right. \\
+ & \frac{1}{2 \lambda+1}\left[-2 \rho \epsilon_{i}^{k} h_{k j}^{\prime \prime}-\epsilon_{i}^{k} h_{k j}^{\prime}+\frac{1}{2} \tilde{A}_{i j}[h]\right.  \tag{7.6}\\
& \left.\left.+\frac{1}{4} \partial^{k} \partial_{k} h_{i j}-\frac{1}{4} \partial_{i} \partial^{k} h_{k j}\right]\right), \\
\frac{\delta I_{2, \lambda, \text { tot }}}{\delta h^{i j}}= & \frac{1}{16 \pi G_{N}(2 \lambda+1)} \rho\left(\delta_{i}^{k}+\epsilon_{i}^{k}\right) h_{k j}^{\prime} .
\end{align*}
$$

To obtain the one-point functions we follow the same reasoning as in section 4.4. We have two independent variables, $h_{(0) i j}$ and $h_{(-2 \lambda) i j}$, for which we define the corresponding CFT operators $T_{i j}$ and $X_{i j}$, with $T_{i j}$ again the energy-momentum tensor of the theory. To find their one-point functions, we first observe that:

$$
\begin{equation*}
h_{(0)}^{i j}=\lim _{\rho \rightarrow 0}\left(h^{i j}+\frac{1}{\lambda} h^{i j} \rho\right) \quad h_{(-2 \lambda)}^{i j}=\lim _{\rho \rightarrow 0}\left(-\frac{1}{\lambda} h^{\prime i j} \rho^{\lambda+1}\right) \tag{7.7}
\end{equation*}
$$

where we note that indices are raised with $\eta^{i j}$. From these expressions we find:

$$
\begin{align*}
\left\langle X_{i j}\right\rangle & \equiv \frac{-4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta I_{2, \lambda, \text { tot }}}{\delta h_{(-2 \lambda)}^{i j}}=\lim _{\rho \rightarrow 0}\left(\lambda \rho^{-1-\lambda} \frac{4 \pi}{\sqrt{-g}} \frac{\delta I_{2, \lambda, \text { tot }}}{\delta h^{i j}}-\rho^{-\lambda} \frac{4 \pi}{\sqrt{-g}} \frac{\delta I_{2, \lambda, \text { tot }}}{\delta h^{i j}}\right)_{L} \\
\left\langle T_{i j}\right\rangle & \equiv \frac{4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta I_{2, \lambda, \text { tot }}}{\delta h_{(0)}^{i j}}=\lim _{\rho \rightarrow 0} \frac{4 \pi}{\sqrt{-g}} \frac{\delta I_{2, \lambda, \text { tot }}}{\delta h^{i j}}, \tag{7.8}
\end{align*}
$$

where the signs originate from the reasoning in appendix B , plus an extra sign arising from the fact that $g^{i j}=\eta^{i j}-h^{i j}$. We inserted a factor of $4 \pi$ in the definition of $X_{i j}$ for later convenience. After substitution of (7.2) these expressions lead to the following finite one-point functions:

$$
\begin{align*}
\left\langle T_{i j}\right\rangle= & \frac{1}{4 G_{N}}\left\{\left(\delta_{i}^{k}-\frac{1}{2 \lambda+1} \epsilon_{i}^{k}\right) h_{(2) k j}-\eta_{i j} \operatorname{tr}\left(h_{(2)}\right)\right. \\
& \left.\quad+\frac{1}{2(2 \lambda+1)} \bar{P}_{i}^{k}\left(\partial^{l} \partial_{l} h_{(0) k j}-\partial_{j} \partial^{l} h_{(0) k l}\right)\right\}, \\
\left\langle X_{i j}\right\rangle= & \frac{\lambda(1+\lambda)}{2 G_{N}(2 \lambda+1)}\left(h_{(2+2 \lambda) i j}\right)_{L} . \tag{7.9}
\end{align*}
$$

Symmetrization in $i$ and $j$ is again understood in these expressions.

### 7.2 Two-point functions

Just as in section 6.3, we can use the equations (6.21) and (6.22) (with the $K_{\mu}$ choice for the Bessel function) to find exact solutions to the linearized equations of motion. Asymp-
totically, they behave as follows:

$$
\begin{align*}
& h_{z \bar{z}}=h_{(0) z \bar{z}}+\rho h_{(2) z \bar{z}}+\frac{1}{2(\lambda-1)(2 \lambda+1)} \partial^{2} h_{(-2 \lambda) \bar{z} \bar{z}} \rho^{1-\lambda}+\ldots, \\
& h_{\bar{z} \bar{z}}=h_{(-2 \lambda) \bar{z} \bar{z}} \rho^{-\lambda}+h_{(0) \bar{z} \bar{z}}+\frac{1}{2(\lambda-1)} \bar{\partial} \partial h_{(-2 \lambda) \bar{z} \bar{z}} \rho^{1-\lambda}+\frac{\bar{\partial}}{\partial} h_{(2) z \bar{z}} \rho+\ldots,  \tag{7.10}\\
& h_{z z}=h_{(0) z z}+\frac{\partial}{\bar{\partial}} h_{(2) z \bar{z}} \rho+\frac{2^{-4 \lambda+2}}{(\lambda+1)} \frac{\Gamma(-2 \lambda-1)}{\Gamma(2 \lambda+1)} q^{4 \lambda-2} \partial^{4} h_{(-2 \lambda) \bar{z} \bar{z}} \rho^{\lambda+1}+\ldots,
\end{align*}
$$

with same trace condition as was given for $\mu=1$ in (6.33),

$$
\begin{equation*}
h_{(2) z \bar{z}}=-\frac{1}{2} \partial^{2} h_{(0) \bar{z} \bar{z}}-\frac{1}{2} \bar{\partial}^{2} h_{(0) z z}+\bar{\partial} \partial h_{(0) z \bar{z}} \tag{7.11}
\end{equation*}
$$

and integration constants $h_{(0) \bar{z} \bar{z}}, h_{(0) z z}, h_{(0) z \bar{z}}$ and $h_{(-2 \lambda) \bar{z} \bar{z}}$; these are as anticipated the sources for the dual operators.

We can substitute this solution in (7.9) to find the one-point functions:

$$
\begin{align*}
\left\langle X_{z z}\right\rangle & =\frac{2^{-4 \lambda+1} \lambda^{2}}{G_{N}} \frac{\Gamma(-2 \lambda-1)}{\Gamma(2 \lambda+2)} q^{4 \lambda-2} \partial^{4} h_{(-2 \lambda) \bar{z} \bar{z}} \\
\left\langle T_{\bar{z} \bar{z}}\right\rangle & =\frac{2 \lambda+2}{4 G_{N}(2 \lambda+1)} \frac{\bar{\partial}}{\partial} h_{(2) z \bar{z}}+\text { local }  \tag{7.12}\\
\left\langle T_{z \bar{z}}\right\rangle & =\text { local } \\
\left\langle T_{z z}\right\rangle & =\frac{2 \lambda}{4 G_{N}(2 \lambda+1)} \frac{\partial}{\bar{\partial}} h_{(2) z \bar{z}} .
\end{align*}
$$

From these expressions we obtain the following nonvanishing two-point functions:

$$
\begin{align*}
\left\langle T_{\bar{z} \bar{z}}(z, \bar{z}) T_{\bar{z} \bar{z}}(0)\right\rangle & =\frac{i \pi}{2 G_{N}} \frac{\lambda+1}{2 \lambda+1} \frac{\bar{\partial}^{3}}{\partial} \delta^{2}(z, \bar{z})=\frac{3}{2 G_{N}} \frac{\lambda+1}{2 \lambda+1} \frac{1}{\bar{z}^{4}} \\
\left\langle T_{z z}(z, \bar{z}) T_{z z}(0)\right\rangle & =\frac{i \pi}{2 G_{N}} \frac{\lambda}{2 \lambda+1} \frac{\partial^{3}}{\bar{\partial}} \delta^{2}(z, \bar{z})=\frac{3}{2 G_{N}} \frac{\lambda}{2 \lambda+1} \frac{1}{z^{4}} \\
\left\langle X_{z z}(z, \bar{z}) X_{z z}(0)\right\rangle & =i \frac{4 \pi}{\sqrt{-g_{(0)}}} \frac{\delta}{\delta h_{(-2 \lambda)}^{z z}(z, \bar{z})}\langle X(0)\rangle=2 \pi i \frac{\delta}{\delta h_{(-2 \lambda) \bar{z} \bar{z}}(z, \bar{z})}\left\langle X_{z z}(0)\right\rangle  \tag{7.13}\\
& =\frac{i \pi 2^{-4 \lambda+2} \lambda^{2}}{G_{N}} \frac{\Gamma(-2 \lambda-1)}{\Gamma(2 \lambda+2)} q^{4 \lambda-2} \partial^{4} \delta^{2}(z, \bar{z}) \\
& =\frac{-1}{2 G_{N}} \frac{\lambda(\lambda+1)(2 \lambda+3)}{2 \lambda+1} \frac{1}{z^{2 \lambda+4} \bar{z}^{2 \lambda}}
\end{align*}
$$

where the computation of the two-point function of the energy-momentum tensor is completely analogous to the previous section and we used the identity (6.40). Comparing now with (6.44) we read off that:

$$
\begin{equation*}
\left(c_{L}, c_{R}\right)=\frac{3}{G_{N}}\left(\frac{\lambda}{2 \lambda+1}, \frac{\lambda+1}{2 \lambda+1}\right)=\frac{3}{2 G_{N}}\left(1-\frac{1}{\mu}, 1+\frac{1}{\mu}\right) \tag{7.14}
\end{equation*}
$$

and from the last line in (7.13) we also find that $X$ has weights $\left(h_{L}, h_{R}\right)=(2+\lambda, \lambda)=$ $\frac{1}{2}(\mu+3, \mu-1)$. Both expressions agree with [3].

The limit $\boldsymbol{\lambda} \rightarrow \mathbf{0}$ and logarithmic CFT. As $\lambda \rightarrow 0$, we find that the $\langle T T\rangle$-correlators return to the values given in section 6.4. On the other hand, the $\langle X X\rangle$-correlator vanishes, but we also find that the definitions for $X_{z z}$ and $T_{z z}$ as given in (7.8) coincide in this limit (up to a sign). To remedy this we can introduce a new field,

$$
\begin{equation*}
t_{z z}=-\frac{1}{\lambda} X_{z z}-\frac{1}{\lambda} T_{z z}, \tag{7.15}
\end{equation*}
$$

after which we can take $\lambda \rightarrow 0$ in (7.8) and obtain (4.36) (up to a sign from the fact that $\left.g^{i j}=\eta^{i j}-h^{i j}\right)$. We obtain for the nonzero two-point functions:

$$
\begin{align*}
\left\langle t_{z z}(z, \bar{z}) T_{z z}(0)\right\rangle & =-\frac{3}{2 G_{N}} \frac{1}{2 \lambda+1} \frac{1}{z^{4}}=\frac{-3 /\left(2 G_{N}\right)}{z^{4}}+\ldots \\
\left\langle t_{z z}(z, \bar{z}) t_{z z}(0)\right\rangle & =\frac{B_{m}+3 /\left(G_{N}\right) \log \left(m^{2}|z|^{2}\right)}{z^{4}}+\ldots \tag{7.16}
\end{align*}
$$

where the dots represent terms that vanish as $\lambda \rightarrow 0$. These are exactly the same correlators as in section 6.4. The term $B_{m}$ can again be removed by a redefinition of $t_{z z}$ and from (7.16) we again see that $b=-3 / G_{N}$.

In appendix D we discuss the degeneration of a CFT to a logarithmic CFT as $c_{L} \rightarrow 0$ following Kogan and Nichols [49]. Their $c_{L} \rightarrow 0$ limit is precisely the same limit as taken here, i.e. the logarithmic partner of the stress energy tensor originates from another primary operator whose dimension approaches $(2,0)$ in the $c_{L} \rightarrow 0$ limit. Given such a limiting procedure, the anomaly $b$ is obtained by inverting the relation between $\lambda$ (which is the right-moving weight of $X$ ) and $c_{L}$ given above and using (D.9) in appendix D. This results in $b=-\lim _{c_{R} \rightarrow 0} c_{L} / \lambda\left(c_{L}\right)=-3 / G_{N}$ and thus agrees with (7.16). Note that there are other distinct approaches to taking a $c \rightarrow 0$ limit, see [50] for a review, but it is the Kogan-Nichols approach which is realized holographically here.

Energy computations. In Lorentzian signature and in global coordinates, the insertions of the operators $X_{z z}, T_{z z}$ or $T_{\bar{z} \bar{z}}$ in the infinite past creates the massive, left-moving or rightmoving graviton states discussed in [3]. In [3] the energy of these states was computed in the bulk and we are now able to give a CFT interpretation of their results.

For the states created by the operators $X_{z z}, T_{z z}, T_{\bar{z} \bar{z}}$, the equations (70)-(72) in [3] give energies of the form:

$$
\begin{align*}
X_{z z}: & & E_{M}=\frac{-1}{8 G_{N}}\left(\mu-\frac{1}{\mu}\right)\left(h_{L}+h_{R}\right)[\ldots], \\
T_{z z}: & & E_{L}=\frac{-1}{4 G_{N}}\left(-1+\frac{1}{\mu}\right)[\ldots],  \tag{7.17}\\
T_{\bar{z} \bar{z}}: & & E_{R}=\frac{-1}{4 G_{N}}\left(-1-\frac{1}{\mu}\right)[\ldots] .
\end{align*}
$$

The expressions in square brackets are positive, but their exact value depends on the normalization of the solutions to the linearized equations of motion in [3] and is therefore arbitrary. We can thus only compare the overall sign of the energies (7.17) with our results. Notice that we put in an extra factor of the left- plus right-moving weight from
each operator, which for $T_{z z}$ and $T_{\bar{z} \bar{z}}$ are just factors of 2 ; in [3] such factors comes from a time derivative of the bulk modes and we will see similar factors appearing below.

Following the usual CFT logic, we may obtain the energies of a state by computing three-point functions. For example, for the massive mode we need to compute

$$
\begin{equation*}
\left\langle X_{z z}\right| T_{z z}(z)\left|X_{z z}\right\rangle, \tag{7.18}
\end{equation*}
$$

with

$$
\begin{equation*}
\left|X_{z z}\right\rangle=X_{z z}(0,0)|0\rangle, \quad\left\langle X_{z z}\right|=\lim _{z, \bar{z} \rightarrow \infty}\langle 0| X_{z z}(z, \bar{z}) z^{2 \lambda+4} \bar{z}^{2 \lambda} . \tag{7.19}
\end{equation*}
$$

The usual Ward identity:

$$
\begin{equation*}
\left\langle X_{z z}\left(z_{1}\right) T_{z z}(z) X_{z z}\left(z_{2}\right)\right\rangle=\sum_{i \in\{1,2\}}\left(\frac{h_{L}}{\left(z-z_{i}\right)^{2}}+\frac{1}{z-z_{i}} \frac{\partial}{\partial z_{i}}\right)\left\langle X_{z z}\left(z_{1}\right) X_{z z}\left(z_{2}\right)\right\rangle \tag{7.20}
\end{equation*}
$$

results in:

$$
\begin{equation*}
\left\langle X_{z z}\right| T_{z z}(z)\left|X_{z z}\right\rangle=\frac{C_{X} h_{L}}{z^{2}} \tag{7.21}
\end{equation*}
$$

where $C_{X}$ is the normalization of the $\langle X X\rangle$-correlator,

$$
\begin{align*}
\left\langle X_{z z}(z, \bar{z}) X_{z z}(0)\right\rangle & =\frac{C_{X}}{z^{4+2 \lambda} \bar{z}^{2 \lambda}},  \tag{7.22}\\
C_{X}=\frac{-1}{2 G_{N}} \frac{\lambda(\lambda+1)(2 \lambda+3)}{2 \lambda+1} & =\frac{-1}{8 G_{N}}\left(\mu-\frac{1}{\mu}\right)(\mu+2) .
\end{align*}
$$

Note that the magnitude (but not the sign) of $C_{X}$ can change by changing the normalization of the operator $X$. This is the counterpart of the arbitrariness of the quantities in the square brackets of (7.17) due to the normalization ambiguity of the solutions to the linearized equations.

By using the Virasoro algebra one may also obtain that:

$$
\begin{equation*}
\left\langle T_{z z}\right| T_{z z}(z)\left|T_{z z}\right\rangle=\langle 0| L_{2} \sum_{m \in \mathbb{Z}} L_{m} z^{-m-2} L_{-2}|0\rangle=\frac{c_{L}}{z^{2}} \tag{7.23}
\end{equation*}
$$

with $c_{L}$ the left-moving central charge defined in (7.14). The computation involving $T_{\bar{z} \bar{z}}$ is completely analogous, and of course the mixed three-point functions involving $T_{z z}$ and $T_{\bar{z} \bar{z}}$ vanish. To transfer these results to the cylinder we use the conformal transformation:

$$
\begin{equation*}
z=\exp (i w) \tag{7.24}
\end{equation*}
$$

whose Schwarzian derivative is $1 / 2$. We then find the following three-point functions on the cylinder:

$$
\begin{align*}
\left\langle X_{w w}\right| T_{w w}(w)+T_{\bar{w} \bar{w}}(\bar{w})-\frac{c_{L}+c_{R}}{24}\left|X_{w w}\right\rangle & =C_{X}\left(h_{L}+h_{R}\right) \\
& =\frac{-1}{8 G_{N}}\left(\mu-\frac{1}{\mu}\right)\left(h_{L}+h_{R}\right)(\mu+2), \\
\left\langle T_{w w}\right| T_{w w}(w)+T_{\bar{w} \bar{w}}(\bar{w})-\frac{c_{L}+c_{R}}{24}\left|T_{w w}\right\rangle & =c_{L}=\frac{3}{2 G_{N}}\left(1-\frac{1}{\mu}\right),  \tag{7.25}\\
\left\langle T_{\bar{w} \bar{w}}\right| T_{w w}(w)+T_{\bar{w} \bar{w}}(\bar{w})-\frac{c_{L}+c_{R}}{24}\left|T_{\bar{w} \bar{w}}\right\rangle & =c_{R}=\frac{3}{2 G_{N}}\left(1+\frac{1}{\mu}\right) .
\end{align*}
$$

Let us now compare these results with [3]. Notice first of all that the zero-point of energy in that paper is that of global AdS, which is why we explicitly subtracted the Casimir energy in the above expressions. Comparing now (7.25) with (7.17) we indeed find the same structure and precisely the same signs. The computations are therefore in agreement.

Finally, notice that in a CFT one usually divides the expressions in (7.25) by the norm of the state (e.g. $\left\langle X_{z z} \mid X_{z z}\right\rangle$ ) to obtain energies that are precisely equal to the conformal weights of the operators creating the state. On the other hand, the energies computed using bulk methods as in [3] are the unnormalized energies of (7.25) and therefore extra signs may arise if a state has a negative norm. This explains the sign difference between the conformal weights and the energies found in [3].

## 8 Conclusions

By implementing the AdS/CFT dictionary for topologically massive gravity, we were able to provide further evidence for its duality at $\mu=1$ to a logarithmic conformal field theory. The expressions for the two-point functions indicate problems with unitarity and positivity as we find zero-norm states at $\mu=1$, negative-norm states at $\mu \neq 1$ and negative conformal weights at $\mu<1$. It therefore seems problematic to consider the full TMG as a fundamental theory, but this duality could nonetheless have interesting applications to condensed matter systems. For example, $c=0$ LCFTs arise in the description of critical systems with quenched disorder and in several other contexts.

One may try to restrict to the right-moving sector of the theory [17], which could yield a consistent chiral theory. In order for this sector to decouple a necessary requirement is that the $\langle t \bar{T} \bar{T}\rangle$ three-point function should vanish. This was shown to be the case in the discussion of [49], see their equation (42), and their analysis can be adapted to the case of interest, namely when only $c_{L} \rightarrow 0$, leading to the same result. This suggests that one can indeed truncate to the right-moving sector, but it would be interesting to extend our analysis and verify the vanishing of this 3 -point function by a bulk computation.

One may also perform a holographic analysis for the 'warped' solutions found in [39]. The asymptotics in these cases are discussed in appendix E and indicate qualitatively different UV behavior for the dual field theory; it would be interesting to extend the holographic setup to this class of solutions. A similar procedure could also be followed to analyze the 'new massive gravity' of [51] around AdS solutions. This would allow us to find out more about the possible dual CFTs.

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## A Derivation of the equations of motion

In this appendix we derive the equations of motion in Fefferman-Graham coordinates, where the metric has the form

$$
\begin{equation*}
d s^{2}=\frac{d \rho^{2}}{4 \rho^{2}}+\frac{1}{\rho} g_{i j}(x, \rho) d x^{i} d x^{j} \tag{A.1}
\end{equation*}
$$

In this section we raise indices using $g^{i j}$ and the covariant derivative $\nabla_{i}$ and the twodimensional antisymmetric tensor $\epsilon_{i j}$ are also defined using $g_{i j}$. In the metric (A.1) the nonzero connection coefficients are:

$$
\begin{array}{ll}
\Gamma_{\rho \rho}^{\rho}=-\frac{1}{\rho} & \Gamma_{\rho j}^{i}=-\frac{1}{2 \rho} g_{j}^{i}+\frac{1}{2}\left(g^{-1} g^{\prime}\right)_{j}^{i} \\
\Gamma_{i j}^{\rho}=2 g_{i j}-2 \rho g_{i j}^{\prime} & \Gamma_{j k}^{i}=\Gamma_{j k}^{i}(g)
\end{array}
$$

where the index $\rho$ now denotes the coordinate $\rho$ and a prime denotes radial derivative. The curvature tensor becomes:

$$
\begin{align*}
R_{\rho i j}^{k}(G) & =\frac{1}{2} g^{k l}\left(\nabla_{l} g_{i j}^{\prime}-\nabla_{j} g_{i l}^{\prime}\right) \\
R_{i \rho j}^{\rho}(G) & =-2 \rho\left(g_{i j}^{\prime \prime}-\frac{1}{2}\left(g^{\prime} g^{-1} g^{\prime}\right)_{i j}\right)-\frac{1}{\rho} g_{i j}  \tag{A.4}\\
R_{i j k}^{l}(G) & =R_{i j k}^{l}(g)+\left(\frac{1}{\rho} g_{i}^{l} g_{j k}+g_{j}^{l} g_{i k}^{\prime}+g^{m l} g_{i k} g_{m j}^{\prime}+\rho g^{l m} g_{i m}^{\prime} g_{j k}^{\prime}-(i \leftrightarrow j)\right)
\end{align*}
$$

The Einstein part of the equation of motion, $R_{\mu \nu}+2 G_{\mu \nu}$, is given by:

$$
\begin{align*}
R_{\rho \rho}(G)+2 G_{\rho \rho} & =-\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{1}{4} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right) \\
R_{i \rho}(G)+2 G_{i \rho} & =\frac{1}{2} \nabla^{j} g_{j i}^{\prime}-\frac{1}{2} \nabla_{i} \operatorname{tr}\left(g^{-1} g^{\prime}\right) \\
R_{i j}(G)+2 G_{i j} & =\frac{1}{2} R(g) g_{i j}+g_{i j} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\rho\left[-2 g_{i j}^{\prime \prime}-g_{i j}^{\prime} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+2\left(g^{\prime} g^{-1} g^{\prime}\right)_{i j}\right] \tag{A.5}
\end{align*}
$$

where we used that in two dimensions

$$
\begin{equation*}
R_{i j k l}=\frac{1}{2} R\left[g_{i k} g_{l j}-(l \leftrightarrow k)\right], \quad \quad R_{i k}=\frac{1}{2} R g_{i k} \tag{A.6}
\end{equation*}
$$

The trace equation $R=-6$ now becomes:

$$
\begin{equation*}
-4 \rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+3 \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)-\rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}+R(g)+2 \operatorname{tr}\left(g^{-1} g^{\prime}\right)=0 \tag{A.7}
\end{equation*}
$$

We use $\epsilon^{\rho i j}=2 \rho^{2} \epsilon^{i j}$ to relate the three- and two-dimensional $\epsilon$-tensors. For the Cotton tensor $C_{\mu \nu}$ defined in (2.5) we then find:

$$
\begin{align*}
& C_{\rho \rho}=\frac{1}{4} \epsilon^{i j}\left(\nabla_{i} \nabla^{k} g_{k j}^{\prime}+2 \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right)_{j i}\right), \\
& \begin{aligned}
C_{\rho i}=\frac{1}{2} \epsilon^{j k}\left(\frac{1}{2} g_{i k} \nabla_{j} R-2 \rho \nabla_{j} g_{i k}^{\prime \prime}-\rho \operatorname{tr}\left(g^{-1} g^{\prime}\right) \nabla_{j} g_{i k}^{\prime}\right. & +2 \rho \nabla_{j}\left(g^{\prime} g^{-1} g^{\prime}\right)_{i k} \\
& \left.-\left(g_{i j}-\rho g_{i j}^{\prime}\right) \nabla^{l} g_{l k}^{\prime}\right),
\end{aligned} \\
& \begin{array}{r}
C_{i \rho}=\epsilon_{i}^{k}\left(-\rho \nabla^{l} g_{l k}^{\prime \prime}-\frac{1}{4} \rho \nabla_{k} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)+\frac{1}{2} \rho\left(g^{-1} g^{\prime}\right)_{k}^{j} \nabla^{l} g_{l j}^{\prime}+\rho\left(g^{-1} g^{\prime}\right)_{l}^{j} \nabla^{l} g_{j k}^{\prime}\right. \\
\\
\\
\left.+\frac{1}{2} \nabla_{k} \operatorname{tr}\left(g^{-1} g^{\prime}\right)-\frac{1}{2} \nabla^{j} g_{j k}^{\prime}\right),
\end{array} \\
& \begin{aligned}
C_{i j}=2 \rho \epsilon_{i}^{k}\left(g_{j k}[ \right. & \left.-\frac{1}{2} R^{\prime}-\frac{1}{4 \rho} R-\frac{1}{2 \rho} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right]-\frac{1}{4} R g_{j k}^{\prime} \\
& +\frac{1}{2} \nabla_{k} \nabla^{m} g_{m j}^{\prime}-\frac{1}{2} \nabla_{k} \nabla_{j}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+2 \rho g_{j k}^{\prime \prime \prime}+g_{k j}^{\prime \prime}\left[3+\rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right] \\
& +g_{k j}^{\prime}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)+\rho\left(\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right)^{\prime}-\rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{1}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right] \\
& +\left(g^{\prime} g^{-1} g^{\prime}\right)_{k j}\left[-3-\frac{1}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]-3 \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right)_{k j}-2 \rho\left(g^{\prime} g^{-1} g^{\prime \prime}\right)_{k j} \\
& \left.+3 \rho\left(g^{\prime} g^{-1} g^{\prime} g^{-1} g^{\prime}\right)_{k j}\right) .
\end{aligned}
\end{align*}
$$

With these expressions we indeed find that $C_{\mu}^{\mu}=0, C_{\rho i}=C_{i \rho}$ and $C_{i j}=C_{j i}$. To verify this we used the Cayley-Hamilton identity,

$$
\begin{equation*}
\frac{1}{2} g_{j l}\left(\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}-\operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right)+\left(g^{\prime} g^{-1} g^{\prime}\right)_{j l}-g_{j l}^{\prime} \operatorname{tr}\left(g^{-1} g^{\prime}\right)=0, \tag{A.9}
\end{equation*}
$$

the radial derivative of the two-dimensional Ricci tensor,

$$
\begin{equation*}
R_{i k}^{\prime}=\frac{1}{2}\left(\nabla^{l} \nabla_{i} g_{k l}^{\prime}+\nabla^{l} \nabla_{k} g_{i l}^{\prime}-\nabla^{a} \nabla_{a} g_{i k}^{\prime}-\nabla_{i} \nabla_{k} \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right), \tag{A.10}
\end{equation*}
$$

as well as the identity for the two-dimensional $\epsilon$-symbol,

$$
\begin{equation*}
\epsilon_{i j} \epsilon_{k l}=-g_{i k} g_{j l}+g_{i l} g_{j k} \tag{A.11}
\end{equation*}
$$

As $C_{i j}$ is symmetric, we can also rewrite it as $\frac{1}{2}\left(C_{i j}+C_{j i}\right)$ which allows us to drop the term proportional to $\epsilon_{i}{ }^{k} g_{k j}$. This, the expression for $R$ given in (A.7), and further application of the Cayley-Hamilton theorem eventually give:

$$
\begin{align*}
C_{i j}=\rho \epsilon_{i}^{k} & \left(\frac{1}{2} \nabla_{k} \nabla^{m} g_{m j}^{\prime}-\frac{1}{2} \nabla_{k} \nabla_{j}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+2 \rho g_{j k}^{\prime \prime \prime}+g_{k j}^{\prime \prime}\left[3+\rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]\right. \\
& +g_{k j}^{\prime}\left[-\frac{3}{2} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{3}{4} \rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}-\rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{7}{4} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right] \\
& \left.-3 \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right)_{k j}-2 \rho\left(g^{\prime} g^{-1} g^{\prime \prime}\right)_{k j}\right)+i \leftrightarrow j . \tag{A.12}
\end{align*}
$$

Combining the above expressions (A.5) and (A.8) leads to the full equations of motion which are given by:

$$
\begin{array}{r}
-\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{1}{4} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)+\frac{1}{4 \mu} \epsilon^{i j}\left(\nabla_{i} \nabla^{k} g_{k j}^{\prime}+2 \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right)_{j i}\right)=0, \\
\frac{1}{2} \nabla^{j} g_{j i}^{\prime}-\frac{1}{2} \nabla_{i} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{1}{2 \mu} \epsilon^{j k}\left(\frac{1}{2} g_{i k} \nabla_{j} R+g_{i k} \nabla^{l} g_{l j}^{\prime}\right. \\
\left.+\rho\left[-2 \nabla_{j} g_{i k}^{\prime \prime}-\operatorname{tr}\left(g^{-1} g^{\prime}\right) \nabla_{j} g_{i k}^{\prime}+2 \nabla_{j}\left(g^{\prime} g^{-1} g^{\prime}\right)_{i k}+g_{i j}^{\prime} \nabla^{l} g_{l k}^{\prime}\right]\right)=0,  \tag{A.13}\\
(\text { A.13) } \\
\left(\operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)-\frac{3}{4} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)+\frac{1}{4}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right) g_{i j}-g_{i j}^{\prime \prime}-\frac{1}{2} g_{i j}^{\prime} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\left(g^{\prime} g^{-1} g^{\prime}\right)_{i j} \\
+\frac{1}{\mu} \epsilon_{i}^{k}\left(\frac{1}{2} \nabla_{k} \nabla^{m} g_{m j}^{\prime}-\frac{1}{2} \nabla_{k} \nabla_{j}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+2 \rho g_{j k}^{\prime \prime \prime}+g_{k j}^{\prime \prime}\left[3+\rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]\right. \\
+g_{k j}^{\prime}\left[-\frac{3}{2} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{3}{4} \rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}-\rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{7}{4} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right] \\
\left.-3 \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right)_{k j}-2 \rho\left(g^{\prime} g^{-1} g^{\prime \prime}\right)_{k j}\right)+i \leftrightarrow j=0,
\end{array}
$$

where we emphasize that the symmetrization in the last equation concerns all the terms. We can use the ( $\rho \rho$ ) equation of motion to simplify the $(i j)$ equation of motion to:

$$
\begin{align*}
& \left(\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)-\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)+\frac{1}{4}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right) g_{i j}-g_{i j}^{\prime \prime}-\frac{1}{2} g_{i j}^{\prime} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\left(g^{\prime} g^{-1} g^{\prime}\right)_{i j} \\
& +\frac{1}{\mu} \epsilon_{i}^{k}\left(\frac{1}{4} \nabla_{k} \nabla^{m} g_{m j}^{\prime}+\frac{1}{4} \nabla_{j} \nabla^{m} g_{m k}^{\prime}-\frac{1}{2} \nabla_{k} \nabla_{j}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+2 \rho g_{j k}^{\prime \prime \prime}+g_{k j}^{\prime \prime}\left[3+\rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]\right. \\
& +g_{k j}^{\prime}\left[-\frac{3}{2} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{3}{4} \rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}-\rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{7}{4} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right] \\
& \left.-\frac{5}{2} \rho\left(g^{\prime \prime} g^{-1} g^{\prime}\right)_{k j}-\frac{5}{2} \rho\left(g^{\prime} g^{-1} g^{\prime \prime}\right)_{k j}\right)+i \leftrightarrow j=0 . \tag{A.14}
\end{align*}
$$

If we use the first radial derivative of (A.9) we can simplify this further to:

$$
\begin{align*}
& \left(\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)-\frac{1}{4}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right) g_{i j}-g_{i j}^{\prime \prime}+\frac{1}{2} g_{i j}^{\prime} \operatorname{tr}\left(g^{-1} g^{\prime}\right)  \tag{A.15}\\
& +\frac{1}{\mu} \epsilon_{i}^{k}\left(\frac{1}{4} \nabla_{k} \nabla^{m} g_{m j}^{\prime}+\frac{1}{4} \nabla_{j} \nabla^{m} g_{m k}^{\prime}-\frac{1}{2} \nabla_{k} \nabla_{j}\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]+2 \rho g_{j k}^{\prime \prime \prime}+g_{k j}^{\prime \prime}\left[3-\frac{3}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]\right. \\
& \left.+g_{k j}^{\prime}\left[-\frac{3}{2} \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{3}{4} \rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}-\frac{7}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime \prime}\right)+\frac{7}{4} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right]\right)+i \leftrightarrow j=0 .
\end{align*}
$$

We can use the equation of motion to rewrite the Riemann tensor as:

$$
\begin{equation*}
R_{\alpha \beta \gamma \delta}[G]=G_{\alpha \delta} G_{\beta \gamma}-G_{\alpha \gamma} G_{\beta \delta}-\left(\left[\frac{1}{\mu} G_{\alpha \gamma} C_{\beta \delta}-(\alpha \leftrightarrow \beta)\right]-(\gamma \leftrightarrow \delta)\right), \tag{A.16}
\end{equation*}
$$

Using then (A.4) for the Riemann tensor in Fefferman-Graham coordinates we obtain:

$$
\begin{align*}
&-2 g_{i j}^{\prime \prime}+\left(g^{\prime} g^{-1} g^{\prime}\right)_{i j}+\frac{4}{\mu} g_{i j} C_{\rho \rho}+\frac{1}{\mu \rho} C_{i j}=0 \\
& \frac{1}{2}\left(\nabla_{k} g_{i j}^{\prime}-\nabla_{j} g_{i k}^{\prime}\right)=\frac{1}{\mu}\left(g_{i j} C_{\rho k}-g_{i k} C_{\rho j}\right) \\
& \frac{1}{2}\left(g_{i k} g_{j l}-g_{i l} g_{j k}\right)\left(-2 \operatorname{tr}\left(g^{-1} g^{\prime}\right)+\rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}-\rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)\right) \\
&+\left(g_{j l} g_{i k}^{\prime}+g_{i k} g_{j l}^{\prime}+\rho g_{i l}^{\prime} g_{j k}^{\prime}-(i \leftrightarrow j)\right)=0 \tag{A.17}
\end{align*}
$$

Taking the trace $g^{i k} R_{i j k l}$ of the last equation results again in the Cayley-Hamilton identity (A.9). This is also the equation that one obtains from the first equation by eliminating $C_{i j}$ and $C_{\rho \rho}$ using the equations of motion. On the other hand, the second of these equations can alternatively be written as:

$$
\begin{align*}
\left(g^{k j}-\mu \epsilon^{k j}\right) \nabla_{k} g_{i j}^{\prime}-\nabla_{i}( & \left.\operatorname{tr}\left(g^{-1} g^{\prime}\right)+\frac{1}{2} \rho \operatorname{tr}\left(g^{-1} g^{\prime} g^{-1} g^{\prime}\right)-\rho\left[\operatorname{tr}\left(g^{-1} g^{\prime}\right)\right]^{2}\right)  \tag{A.18}\\
& +2 \rho \nabla^{n}\left(g_{i n}^{\prime \prime}-\operatorname{tr}\left(g^{-1} g^{\prime}\right) g_{i n}^{\prime}\right)+\rho\left(g^{-1} g^{\prime}\right)_{i}^{k} \nabla^{l} g_{k l}^{\prime}=0
\end{align*}
$$

## B Wick rotation

Given a Lorentzian theory, the most straightforward way to find the corresponding action in Euclidean signature is to use a complex diffeomorphism:

$$
\begin{equation*}
t=-i \tau . \tag{B.1}
\end{equation*}
$$

After this diffeomorphism (or a similar one using a different coordinate system) the metric generally becomes positive definite and one has to be careful about the definition of the square root in the metric determinant. The signs work out correctly if we define $\sqrt{-1}=$ $-i$ [31]. As in any coordinate system, the antisymmetric tensor is still defined such that $\sqrt{-G} \epsilon^{012}=1$ with $x^{0}$ now the $\tau$-direction. Because of the volume element the $\epsilon$-tensor is now complex and to comply with standard notation we make this explicit by writing $-i \epsilon^{\lambda \mu \nu}=\hat{\epsilon}^{\lambda \mu \nu}$, where $\hat{\epsilon}^{\lambda \mu \nu}$ is the standard antisymmetric tensor in Euclidean coordinates which is defined such that $\sqrt{G} \hat{\epsilon}^{012}=1$.

As for the action of the theory, we find that the diffeomorphism results in $i S_{L} \rightarrow-S_{E}$ with $S_{E}$ the standard Euclidean action. In our case, (2.1) becomes:

$$
\begin{align*}
i S_{L}= & -\frac{1}{16 \pi G_{N}} \int d^{3} x \sqrt{G}(-R+2 \Lambda) \\
& +\frac{i}{32 \pi G_{N} \mu} \int d^{3} x \sqrt{G} \hat{\epsilon}^{\lambda \mu \nu}\left(\Gamma_{\lambda \sigma}^{\rho} \partial_{\mu} \Gamma_{\rho \nu}^{\sigma}+\frac{2}{3} \Gamma_{\lambda \sigma}^{\rho} \Gamma_{\mu \tau}^{\sigma} \Gamma_{\nu \rho}^{\tau}\right) . \tag{B.2}
\end{align*}
$$

Notice that the implicit metric determinant present in the $\epsilon$-symbol cancels the one in the volume element and there is no sign change for the Chern-Simons term. From this
action, we see that a convenient way to determine the Euclidean equations of motion is to replace everywhere

$$
\begin{equation*}
\epsilon^{\lambda \mu \nu} \rightarrow i \hat{\epsilon}^{\lambda \mu \nu}, \quad \quad \epsilon^{i j} \rightarrow i \hat{\epsilon}^{i j} . \tag{B.3}
\end{equation*}
$$

With these replacements the equations of motion become complex, and so do the linearized solutions we find in the main text, but this is not a problem, see [31] for a more extended discussion of this point.

When using component equations, the conversion between Euclidean and Lorentzian signature is most easily done by introducing lightcone coordinates on the Lorentzian side:

$$
\begin{equation*}
u=x+t, \quad v=x-t . \tag{B.4}
\end{equation*}
$$

In these coordinates the metric becomes:

$$
\begin{equation*}
d s^{2}=d u d v \tag{B.5}
\end{equation*}
$$

and we fix the sign of the $\epsilon$-tensor such that $\epsilon_{u v}=-\frac{1}{2}$. The passage to Euclidean signature is then implemented by defining complex coordinates:

$$
\begin{equation*}
z=x+i \tau, \quad \bar{z}=x-i \tau, \tag{B.6}
\end{equation*}
$$

after which the metric $d s^{2}=d \tau^{2}+d x^{2}$ becomes:

$$
\begin{equation*}
d s^{2}=d z d \bar{z} \tag{B.7}
\end{equation*}
$$

The metric determinant in complex coordinates becomes negative again and therefore $\hat{\epsilon}^{i j}$ is complex and $\epsilon^{i j}$ is real. We deduce that the component equations in Euclidean signature can be obtained by the simple replacement

$$
\begin{equation*}
v \rightarrow z, \quad u \rightarrow \bar{z}, \tag{B.8}
\end{equation*}
$$

in the Lorentzian equations of motion, without any modification of the $\epsilon$-tensor.
Incidentally, notice that the operators:

$$
\begin{equation*}
P_{i}^{k}=\frac{1}{2}\left(\delta_{i}^{k}+\epsilon_{i}^{k}\right), \quad \quad \bar{P}_{i}^{k}=\frac{1}{2}\left(\delta_{i}^{k}-\epsilon_{i}^{k}\right), \tag{B.9}
\end{equation*}
$$

take the following form in lightcone coordinates:

$$
\left(\begin{array}{cc}
P_{u}^{u} & P_{u}^{v}  \tag{B.10}\\
P_{v}^{u} & P_{v}^{v}
\end{array}\right)=\left(\begin{array}{ll}
0 & 0 \\
0 & 1
\end{array}\right) \quad\left(\begin{array}{cc}
\bar{P}_{u}^{u} & \bar{P}_{u}^{v} \\
\bar{P}_{v}^{u} & \bar{P}_{v}^{v}
\end{array}\right)=\left(\begin{array}{ll}
1 & 0 \\
0 & 0
\end{array}\right)
$$

so that, if for example $P_{i}^{k} b_{(0) k j}=0$ and $b_{(0) i}^{i}=0$ then only the $b_{(0) u u}$ component can be nonzero. From the above reasoning it follows that these operators take the same form in complex coordinates and therefore only $b_{(0) \bar{z} \bar{z}}$ can be nonzero.

Signs in correlation functions. Our conventions are such that on a Euclidean background metric $g_{i j}$ the energy-momentum tensor is defined as:

$$
\begin{equation*}
T_{E, i j}=\frac{4 \pi}{\sqrt{g}} \frac{\delta S_{E}}{\delta g^{i j}} . \tag{B.11}
\end{equation*}
$$

Notice that we functionally differentiate with respect to the inverse metric. When we analytically continue back to Lorentzian signature, the definition on the right-hand side changes. Namely, from the above discussion it follows that $S_{E}=-i S_{L}$ and $\sqrt{g}=i \sqrt{-g}$, so in Lorentzian signature

$$
\begin{equation*}
T_{L, i j}=-\frac{4 \pi}{\sqrt{-g}} \frac{\delta S_{L}}{\delta g^{i j}} \tag{B.12}
\end{equation*}
$$

In terms of the generating functional of connected correlation functions, $W=\log (Z)$, we find that:

$$
\begin{equation*}
T_{E, i j}=-\frac{4 \pi}{\sqrt{g}} \frac{\delta W_{E}}{\delta g^{i j}}, \quad \quad T_{L, i j}=i \frac{4 \pi}{\sqrt{-g}} \frac{\delta W_{L}}{\delta g^{i j}} \tag{B.13}
\end{equation*}
$$

These expressions lead to the following identity that we use in the main text:

$$
\begin{equation*}
\left\langle T_{i j} \ldots\right\rangle_{g}=i \frac{4 \pi}{\sqrt{-g}} \frac{\delta}{\delta g^{i j}}\langle\ldots\rangle_{g} \tag{B.14}
\end{equation*}
$$

where $\langle\ldots\rangle_{g}$ is an arbitrary correlator in the background metric $g_{i j}$. Notice that this expression holds irrespective of the signature of the metric, provided we define the square root as above.

Now for general correlation functions of an operator $\mathcal{O}$, we customarily define the source-operator coupling in Euclidean signature as:

$$
\begin{equation*}
-\int d^{2} x \sqrt{-g} \phi_{E} \cdot \mathcal{O}_{E} \tag{B.15}
\end{equation*}
$$

with $\phi_{E}$ the Euclidean source and the dot denoting various possible index contractions. Using once more the above conventions, we find that in Lorentzian signature the coupling becomes:

$$
\begin{equation*}
-i \int d^{2} x \sqrt{-g} \phi_{L} \cdot \mathcal{O}_{L} \tag{B.16}
\end{equation*}
$$

and therefore

$$
\begin{equation*}
\left\langle\mathcal{O}_{E}\right\rangle=-\frac{1}{\sqrt{g}} \frac{\delta W_{E}}{\delta \phi_{E}}, \quad\left\langle\mathcal{O}_{L}\right\rangle=i \frac{1}{\sqrt{-g}} \frac{\delta W_{L}}{\delta \phi_{L}} \tag{B.17}
\end{equation*}
$$

This results in the general expression in terms of correlation functions:

$$
\begin{equation*}
\langle\mathcal{O} \ldots\rangle_{\phi}=i \frac{1}{\sqrt{-g}} \frac{\delta}{\delta \phi}\langle\ldots\rangle_{\phi} . \tag{B.18}
\end{equation*}
$$

In the context of AdS/CFT, $W_{E} \sim-S_{E}$ and $W_{L} \sim i S_{L}$ with $S_{E}$ and $S_{L}$ the Euclidean and the Lorentzian on-shell bulk action, respectively. This leads to:

$$
\begin{equation*}
\left\langle\mathcal{O}_{E}\right\rangle=\frac{1}{\sqrt{g}} \frac{\delta S_{E}}{\delta \phi_{E}}, \quad\left\langle\mathcal{O}_{L}\right\rangle=-\frac{1}{\sqrt{-g}} \frac{\delta S_{L}}{\delta \phi_{L}} \tag{B.19}
\end{equation*}
$$

On the other hand, for the energy-momentum tensor one may directly use the formulas (B.11) and (B.12), where now $S_{L}$ and $S_{E}$ are the on-shell bulk action. It was shown in [31] that these expressions, with in particular the above choice of signs, lead to continuous holographic expressions for the one-point functions. For example, in the case of three-dimensional Einstein gravity one finds:

$$
\begin{equation*}
\left\langle T_{i j}\right\rangle=\frac{1}{4 G_{N}}\left(g_{(2) i j}+\frac{1}{2} g_{(0) i j} R\left[g_{(0)}\right]\right) \tag{B.20}
\end{equation*}
$$

independently of the metric signature. In this expression $g_{(0) i j}$ and $g_{(2) i j}$ the leading and subleading terms in the Fefferman-Graham expansion (4.4). Similarly, for a scalar operator $\mathcal{O}$ dual to a bulk scalar field $\Phi$ one finds that:

$$
\begin{equation*}
\langle\mathcal{O}\rangle=-(2 \Delta-d) \phi_{(2 \Delta-d)} \tag{B.21}
\end{equation*}
$$

with $\phi_{(2 \Delta-d)}$ the coefficient of order $z^{\Delta}$ in the radial expansion (3.9). Again, with the above conventions the formula (B.21) holds both in Lorentzian and in Euclidean signature [31].

## C Linearized equations of motion in global coordinates

In this appendix we will present the linearized equations in global coordinates. The usual metric

$$
\begin{equation*}
d s^{2}=-\cosh ^{2}(r) d t^{2}+\sinh ^{2}(r) d \phi^{2}+d r^{2} \tag{C.1}
\end{equation*}
$$

can be put in the Fefferman-Graham form (4.1) by defining

$$
\begin{equation*}
\rho=4 e^{-2 r}, \tag{C.2}
\end{equation*}
$$

after which we obtain:

$$
\begin{equation*}
d s^{2}=-\frac{1}{\rho}\left(1+\frac{1}{2} \rho+\frac{1}{16} \rho^{2}\right) d t^{2}+\frac{1}{\rho}\left(1-\frac{1}{2} \rho+\frac{1}{16} \rho^{2}\right) d \phi^{2}+\frac{d \rho^{2}}{4 \rho^{2}} . \tag{C.3}
\end{equation*}
$$

These coordinates cover all of AdS and are thus global coordinates. Notice that $\partial_{k} g_{i j}=0$ and therefore $\Gamma_{i j}^{k}[g]=0$ (which of course does not imply that $\delta \Gamma_{i j}^{k}$ vanishes in the linearized equations). We also find that:

$$
\begin{equation*}
\left(g^{\prime} g^{-1} g^{\prime}\right)_{i j}=2 g_{i j}^{\prime \prime} ; \quad g_{i j}^{\prime \prime}-\frac{1}{2} \operatorname{tr}\left(g^{-1} g^{\prime}\right) g_{i j}^{\prime}=f(\rho) g_{i j} ; \quad \operatorname{tr}\left(g^{-1} g^{\prime}\right)=-2 \rho f(\rho) \tag{C.4}
\end{equation*}
$$

with

$$
\begin{equation*}
f(\rho)=\frac{2}{16-\rho^{2}}, \tag{C.5}
\end{equation*}
$$

which we use to simplify the formulas below. In the expressions below traces are implicitly taken with the aid of $g^{-1}$, that is we write $\operatorname{tr}\left(g^{\prime}\right)$ where before we wrote $\operatorname{tr}\left(g^{-1} g^{\prime}\right)$.

The linearized $(i j)$ equation of motion (A.15) becomes:

$$
\begin{align*}
& -h_{i j}^{\prime \prime}-\rho f(\rho) h_{i j}^{\prime}+f(\rho) h_{i j}+g_{i j}\left[\frac{1}{2} \operatorname{tr}\left(h^{\prime \prime}\right)-\frac{1}{2} \operatorname{tr}\left(h g^{-1} g^{\prime \prime}\right)+\rho f(\rho)\left(\operatorname{tr}\left(h^{\prime}\right)-\operatorname{tr}\left(g^{\prime} g^{-1} h\right)\right)\right] \\
& +\frac{1}{2} g_{i j}^{\prime}\left[\operatorname{tr}\left(h^{\prime}\right)-\operatorname{tr}\left(g^{\prime} g^{-1} h\right)\right]+\frac{1}{\mu} \epsilon_{i}^{k}\left[\frac{1}{4} \partial_{k} \partial^{l} h_{l j}^{\prime}-\frac{1}{4}\left(g^{-1} g^{\prime}\right)_{j}^{c}\left[\partial_{k} \partial^{l} h_{l c}-\frac{1}{2} \partial_{k} \partial_{c} \operatorname{tr}(h)\right]+(j \leftrightarrow k)\right] \\
& +\frac{1}{\mu} \epsilon_{i}^{k}\left[\frac{1}{4} \partial_{k} \partial_{j} \operatorname{tr}\left(g^{\prime} g^{-1} h\right)-\frac{1}{2} \partial_{k} \partial_{j} \operatorname{tr}\left(h^{\prime}\right)+2 \rho h_{j k}^{\prime \prime \prime}+3\left(1+\rho^{2} f(\rho)\right)\left[h_{j k}^{\prime \prime}+\rho f(\rho) h_{j k}^{\prime}-f(\rho) h_{k j}\right]\right] \\
& +\frac{1}{\mu} \epsilon_{i}^{k} g_{j k}^{\prime}\left[-\frac{3}{2}\left(1+\rho^{2} f(\rho)\right)\left[\operatorname{tr}\left(h^{\prime}\right)-\operatorname{tr}\left(h g^{-1} g^{\prime}\right)\right]-\frac{7}{2} \rho\left[\operatorname{tr}\left(h^{\prime \prime}\right)+\operatorname{tr}\left(h g^{-1} g^{\prime \prime}\right)-\operatorname{tr}\left(h^{\prime} g^{-1} g^{\prime}\right)\right]\right] \\
& +(i \leftrightarrow j)=0 \tag{C.6}
\end{align*}
$$

The linearized version of the ( $\rho i$ ) equation given in (A.18) becomes:

$$
\begin{align*}
& 2 \rho \partial^{k} h_{i k}^{\prime \prime}+\left(1+4 \rho^{2} f(\rho)\right) \partial^{k} h_{i k}^{\prime}+\mu \epsilon^{j k} \partial_{k} h_{i j}^{\prime}-\frac{1}{2} \mu \epsilon^{j k}\left(g^{-1} g^{\prime}\right)_{j}^{l}\left(\partial_{k} h_{i l}+\partial_{i} h_{k l}-\partial_{l} h_{i k}\right) \\
& -\partial_{i}\left[\rho \operatorname{tr}\left(h^{\prime} g^{-1} g^{\prime}\right)+\left[1+4 \rho^{2} f(\rho)\right] \operatorname{tr}\left(h^{\prime}\right)-\left[\frac{1}{2}+2 \rho^{2} f(\rho)\right] \operatorname{tr}\left(g^{\prime} g^{-1} h\right)-\rho \operatorname{tr}\left(g^{\prime \prime} g^{-1} h\right)\right] \\
& +\left(g^{-1} g^{\prime}\right)_{i}^{k}\left[\rho \partial^{l} h_{k l}^{\prime}-2 \rho \partial_{k} \operatorname{tr}\left(h^{\prime}\right)-\frac{3}{2} \rho \partial_{k} \operatorname{tr}\left(h g^{-1} g^{\prime}\right)-\left[1+4 \rho^{2} f(\rho)\right]\left[\partial^{l} h_{k l}-\frac{1}{2} \partial_{k} \operatorname{tr}(h)\right]\right] \\
& -2 \rho\left(g^{-1} g^{\prime \prime}\right)_{i}^{k}\left[2 \partial^{l} h_{k l}-\partial_{k} \operatorname{tr}(h)\right]=0 \tag{C.7}
\end{align*}
$$

and the $(\rho \rho)$ equation results in:

$$
\begin{align*}
-\operatorname{tr}\left(h^{\prime \prime}\right) & +\operatorname{tr}\left(h^{\prime} g^{-1} g^{\prime}\right)-\operatorname{tr}\left(h g^{-1} g^{\prime \prime}\right)+\frac{1}{2 \mu} \epsilon^{i j}\left[\partial_{i} \partial^{m} h_{m j}^{\prime}-\left(g^{-1} g^{\prime}\right)_{j}^{c}\left(\partial_{i} \partial^{m} h_{m c}-\frac{1}{2} \partial_{i} \partial_{c} \operatorname{tr}(h)\right)\right. \\
& \left.+2 \rho\left(h^{\prime} g^{-1} g^{\prime \prime}\right)_{i j}-2 \rho\left(g^{\prime} g^{-1} h g^{-1} g^{\prime \prime}\right)_{i j}+2 \rho\left(g^{\prime} g^{-1} h^{\prime \prime}\right)_{i j}\right]=0 \tag{C.8}
\end{align*}
$$

## D Some results from LCFT

A logarithmic conformal field theory (LCFT) is a conformal field theory in which logarithmic structure arises in the operator product expansion. Such logarithmic structure arises when there are fields with degenerate scaling dimensions having a Jordan block structure; in any logarithmic conformal field theory one of these degenerate fields becomes a zero norm state coupled to a logarithmic partner. In what follows we will be interested in the simplest situation, in which two operators become degenerate and form a logarithmic pair, denoted by $(C, D)$. If the operator $C$ becomes a zero norm state, the two point functions for this logarithmic pair have the structure:

$$
\begin{align*}
\langle C(z, \bar{z}) C(0)\rangle & =0 ; \quad\langle C(z, \bar{z}) D(0,0)\rangle=\frac{b_{D}}{2 z^{2 h_{L}} \bar{z}^{2 h_{R}}}  \tag{D.1}\\
\langle D(z, \bar{z}) D(0,0)\rangle & =\frac{1}{z^{2 h_{L}} \bar{z}^{2 h_{R}}}\left[-b_{D} \log m^{2}|z|^{2}+B_{D}\right]
\end{align*}
$$

where the conformal weights of both operators are $\left(h_{L}, h_{R}\right)$. The constant $B_{D}$ may be removed by the redefinition $D \rightarrow D-B_{D} C / b_{D}$ but $b_{D}$ has an invariant meaning and is a characteristic of the LCFT. One can easily generalize these formulas to the case when there are $n$ degenerate fields and the Jordan cell is given by an $n \times n$ matrix, in which case the maximal power of the logarithm will be $\log ^{n}|z|$.

In the current context we are interested in the case where the conformal field theory becomes logarithmic as $c_{L} \rightarrow 0$ and one of the logarithmic pair is the holomorphic stress energy tensor. There are several distinct approaches to taking such limits, see [50] for a review, but the limit relevant for us was discussed in Kogan and Nichols [49]. The following is a slightly modified version of the discussion in that paper, in which we take the limit $c_{L} \rightarrow 0$ only in the holomorphic sector.

Consider a conformal field theory with central charges $\left(c_{L}, c_{R}\right)$ and holomorphic/antiholomorphic stress energy tensors $(T(z), \bar{T}(\bar{z}))$ respectively, such that

$$
\begin{equation*}
\langle T(z) T(0)\rangle=\frac{c_{L}}{2 z^{4}} ; \quad\langle\bar{T}(\bar{z}) \bar{T}(0)\rangle=\frac{c_{R}}{2 \bar{z}^{4}} \tag{D.2}
\end{equation*}
$$

Let $V(z, \bar{z})$ be a primary field of dimensions $\left(h_{L}, h_{R}\right)$, normalized as

$$
\begin{equation*}
\langle V(z, \bar{z}) V(0,0)\rangle=\frac{A}{z^{2 h_{L}} \bar{z}^{2 h_{R}}} \tag{D.3}
\end{equation*}
$$

If $T$ is the only $h_{L}=2$ field present (and $\bar{T}$ is the only $h_{R}=2$ field), then the OPE for $V(z, \bar{z})$ is of the form

$$
\begin{equation*}
V(z, \bar{z}) V(0,0) \sim \frac{A}{z^{2 h_{L}} \bar{z}^{2 h_{R}}}\left[1+\frac{2 h_{L}}{c_{L}} z^{2} T(0)+\frac{2 h_{R}}{c_{R}} \bar{z}^{2} \bar{T}(0)+\cdots\right] \tag{D.4}
\end{equation*}
$$

where the ellipses denote operators of higher dimension.
Consider now the limit $c_{L} \rightarrow 0$ with $c_{R}$ finite: if $A$ remains finite in this limit then the OPE is not well-defined. Suppose that as $c_{L}$ approaches zero then there is another field $X$ with dimension $(2+\lambda, \lambda)$ which approaches $(2,0)$; suppose also that its normalization is such that this field contributes to the OPE as

$$
\begin{equation*}
V(z, \bar{z}) V(0,0) \sim \frac{A}{z^{2 h_{L}} \bar{z}^{2 h_{R}}}\left[1+\frac{2 h_{L}}{c_{L}} z^{2} T(0)+\frac{2 h_{R}}{c_{R}} z^{2+\lambda} \bar{z}^{\lambda} X(0,0)+\cdots\right] . \tag{D.5}
\end{equation*}
$$

Let the two-point function of $X$ be given by:

$$
\begin{equation*}
\langle X(z, \bar{z}) X(0,0)\rangle=\frac{B(\lambda)}{z^{4+2 \lambda} \bar{z}^{2 \lambda}} \tag{D.6}
\end{equation*}
$$

whilst $\left\langle T\left(z_{1}\right) X\left(z_{2}, \bar{z}_{2}\right)\right\rangle$ vanishes as they have different dimensions. Now let us define a new field $t(z, \bar{z})$ via

$$
\begin{equation*}
t=-\frac{1}{\lambda} T-\frac{1}{\lambda} X \tag{D.7}
\end{equation*}
$$

In this way the $\operatorname{OPE}(\mathrm{D} .5)$ is rendered well-defined as $c_{L} \rightarrow 0$ :

$$
\begin{equation*}
V(z, \bar{z}) V(0,0) \sim \frac{A}{z^{2 h_{L}} \bar{z}^{2 h_{R}}}\left[1+\frac{2 h_{L}}{b} z^{2}\left[t(0,0)+T(0) \log \left(m^{2}|z|^{2}\right)\right]+\cdots\right] \tag{D.8}
\end{equation*}
$$

provided the parameter $b$, defined as

$$
\begin{equation*}
b \equiv-\lim _{c_{L} \rightarrow 0} \frac{c_{L}}{\lambda\left(c_{L}\right)}=-\frac{1}{\lambda^{\prime}(0)}, \tag{D.9}
\end{equation*}
$$

is finite. As $c_{L} \rightarrow 0$ the two point functions of the pair $(T, t)$ become:

$$
\begin{align*}
\langle T(z) T(0)\rangle & =0 ; \quad\langle T(z) t(0,0)\rangle=\frac{b}{2 z^{4}} ;  \tag{D.10}\\
\langle t(z, \bar{z}) t(0,0)\rangle & =\frac{1}{z^{4}} \lim _{c_{L} \rightarrow 0}\left[-\frac{b}{2 \lambda}+\frac{B}{\lambda^{2}}-2 \lambda B \log \left(m^{2}\left|z^{2}\right|\right)+\cdots\right] .
\end{align*}
$$

For this to be well-defined as $c_{L} \rightarrow 0$,

$$
\begin{equation*}
B\left(c_{L}\right)=\frac{b \lambda}{2}+B_{m} \lambda^{2}+\mathcal{O}\left(\lambda^{3}\right), \tag{D.11}
\end{equation*}
$$

and therefore

$$
\begin{equation*}
\langle t(z, \bar{z}) t(0,0)\rangle=\frac{B_{m}-b \log \left(m^{2}|z|^{2}\right)}{z^{4}} . \tag{D.12}
\end{equation*}
$$

The logarithmic pair ( $T, t$ ) thus indeed has the anticipated two-point function structure given in (D.1). We are interested in the case where $c_{R} \neq 0$, and thus there is no such degeneration in the anti-holomorphic sector. Note that

$$
\begin{equation*}
\langle\bar{T}(\bar{z}) t(0,0)\rangle=0 . \tag{D.13}
\end{equation*}
$$

Recall that the constant $B_{m}$ can be changed by a redefinition of $t$; choosing $t \rightarrow t-B_{m} T / b$ removes the non-logarithmic term in the two point function (D.12).

## E Warped AdS

The metric of global $\mathrm{AdS}_{3}$ can be written in 'warped' form as:

$$
\begin{equation*}
d s^{2}=-\cosh ^{2}(\sigma) d \tau^{2}+\frac{1}{4} d \sigma^{2}+(d u+\sinh (\sigma) d \tau)^{2} \tag{E.1}
\end{equation*}
$$

We can define:

$$
\begin{equation*}
z=2 e^{-\sigma / 2} \quad \sigma=2 \log (z / 2) \tag{E.2}
\end{equation*}
$$

after which the metric becomes:

$$
\begin{equation*}
d s^{2}=\frac{d z^{2}}{z^{2}}-d \tau^{2}+d u^{2}+\left(\frac{4}{z^{2}}-\frac{z^{2}}{4}\right) d u d \tau . \tag{E.3}
\end{equation*}
$$

In this coordinate system it is manifest that this metric is conformally compact. Namely, $z$ can be used as the defining function: in agreement with the discussion in section $3, z$ has a single zero at $z=0$ and the metric:

$$
\begin{equation*}
z^{2} d s^{2}=d z^{2}+4 d u d \tau+\ldots \tag{E.4}
\end{equation*}
$$

is a non-degenerate three-dimensional metric that extends smoothly to $z=0$.

On the other hand, the metric of spacelike warped AdS can be written as:

$$
\begin{equation*}
d s^{2}=\left(-\cosh ^{2}(\sigma)\left(\nu^{2}+3\right)+4 \nu^{2} \sinh ^{2}(\sigma)\right) d \tau^{2}+\frac{d \sigma^{2}}{\nu^{2}+3}+4 \nu^{2} d u^{2}+8 \nu^{2} \sinh (\sigma) d u d \tau \tag{E.5}
\end{equation*}
$$

with $\nu=\mu / 3$. After the coordinate transformation:

$$
\begin{equation*}
\sigma=-\sqrt{\nu^{2}+3} \log (z) \tag{E.6}
\end{equation*}
$$

it becomes asymptotically of the form:

$$
\begin{equation*}
d s^{2}=\frac{d z^{2}}{z^{2}}+3\left(\nu^{2}-1\right) z^{-2 \sqrt{\nu^{2}+3}} d \tau^{2}+8 \nu^{2} z^{-\sqrt{\nu^{2}+3}} d u d \tau+\ldots \tag{E.7}
\end{equation*}
$$

As $z \rightarrow 0$, we find that the terms have a different pole structure and therefore this metric cannot be made regular by multiplication with the usual defining function $z$, unless $\nu^{2}=1$ (which is AdS). Furthermore, the leading term in the induced metric at slices of constant $z$ is proportional to $d \tau^{2}$ and so it is degenerate. Thus the spacetime with metric (E.5) is not conformally compact. Notice that the same conclusion holds for any spacetime whose metric asymptotes to (E.5).

For timelike warped AdS the metric has the form:

$$
\begin{equation*}
d s^{2}=\left(\cosh ^{2}(\sigma)\left(\nu^{2}+3\right)-4 \nu^{2} \sinh ^{2}(\sigma)\right) d u^{2}+\frac{d \sigma^{2}}{\nu^{2}+3}-4 \nu^{2} d \tau^{2}-8 \nu^{2} \sinh (\sigma) d u d \tau \tag{E.8}
\end{equation*}
$$

This is just spacelike warped AdS with the replacement $\tau \rightarrow i u$ and $u \rightarrow i \tau$ and we can immediately draw the same conclusions as for spacelike warped AdS.

For null warped $\operatorname{AdS}$ the metric is given by:

$$
\begin{equation*}
d s^{2}=\frac{d z^{2}}{z^{2}}+\frac{d u d v}{z^{2}} \pm \frac{d u^{2}}{z^{4}} \tag{E.9}
\end{equation*}
$$

which is a solution of TMG with $\mu=3$ or $\nu=1$. We again find a different pole structure for the different terms, as well as a singular leading-order term in the induced metric on slices of constant $z$. Again, no good defining function exists that makes the three-dimensional metric regular on the slice $z=0$ and this manifold is not conformally compact.

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[^0]:    ${ }^{1}$ Solutions of the non-linear equations of motion exhibiting similar asymptotic form were presented earlier in $[13,14]$.

[^1]:    ${ }^{2}$ For the purpose of this introduction we take the manifold to be Euclidean (so in particular $\partial M$ does not contain initial and final hypersurfaces). The Lorentzian case can be dealt with using the formalism of $[30,31]$.

[^2]:    ${ }^{3}$ Ref. [36], appendix E, contains an example of 3d gravity coupled to scalars with $\log ^{2}$ terms in the asymptotic expansion.

[^3]:    ${ }^{4}$ Our conventions differ as follows. Our $T_{i j}$ has an extra $1 / \sqrt{-g}$ as opposed to the analogous object in [43]; indeed, in our case $\hat{T}_{i j}$ is a tensor whereas in [43] it is a tensor density. The overall sign of the energy-momentum tensors is however the same. The connection $\Gamma_{i j}^{k}$ in [43] is defined with an extra minus sign, but the Riemann curvature has the same sign. Finally, we always use a covariant $\epsilon$-symbol whereas this is not the case in [43].

[^4]:    ${ }^{5}$ Alternatively, one can obtain the correlators on $R \times S^{1}$ from the ones on $R^{2}$ by using the fact that $R \times S^{1}$ is conformally related to $R^{2}$ and finite Weyl transformations in the boundary theory can be implemented by specific bulk diffeomorphisms [26] (whose infinitesimal form was derived first in [46]).

